

# ECE 105: Introduction to Electrical Engineering

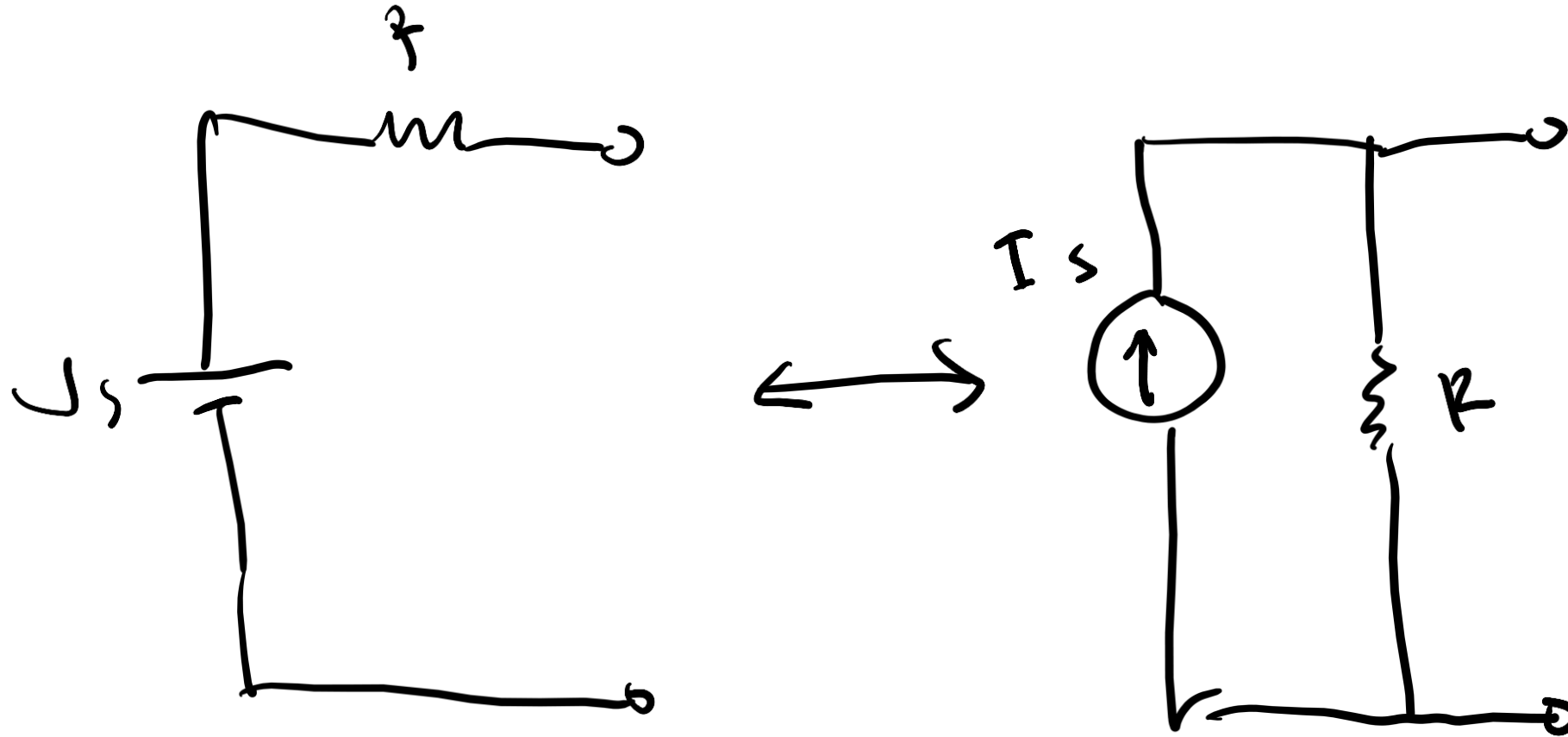
Lecture 7

Circuit Analysis - 3

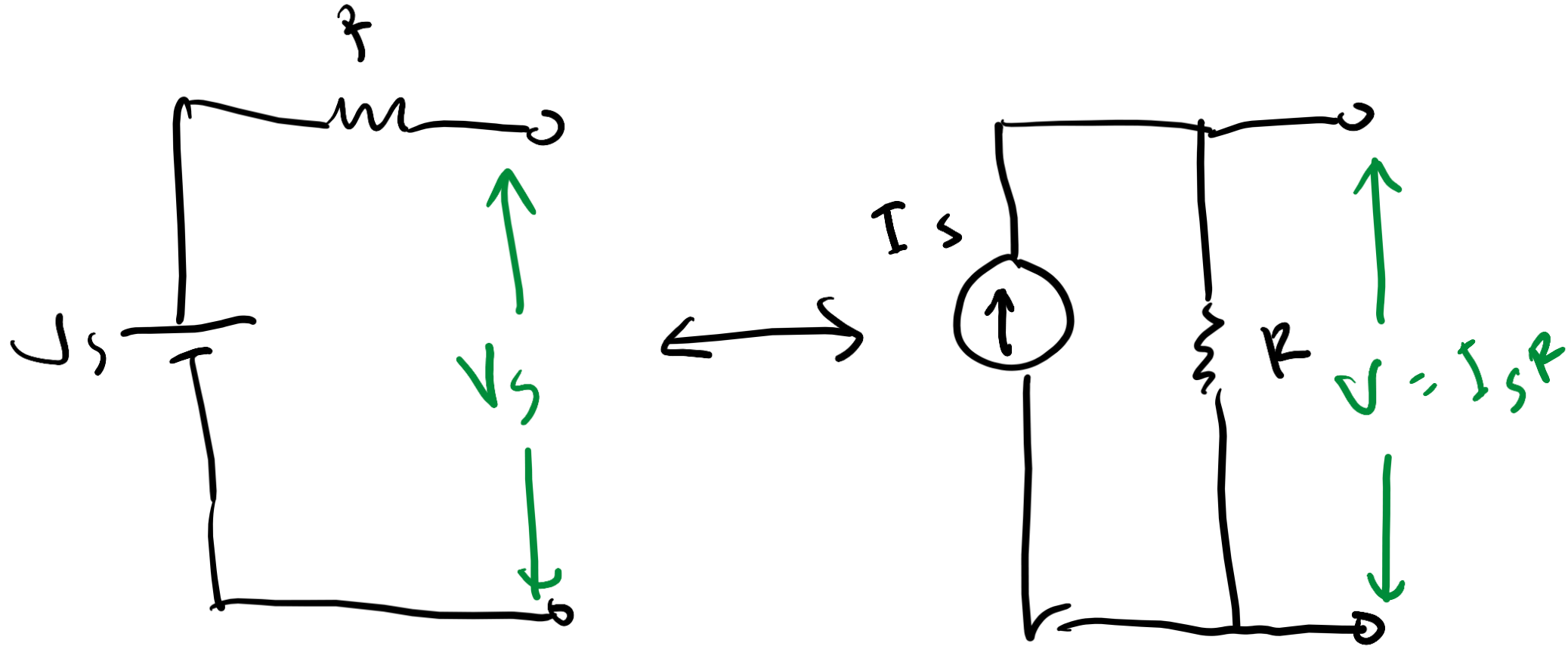
Yasser Khan

Rehan Kapadia

# Source transformation – Voltage $\leftrightarrow$ Current



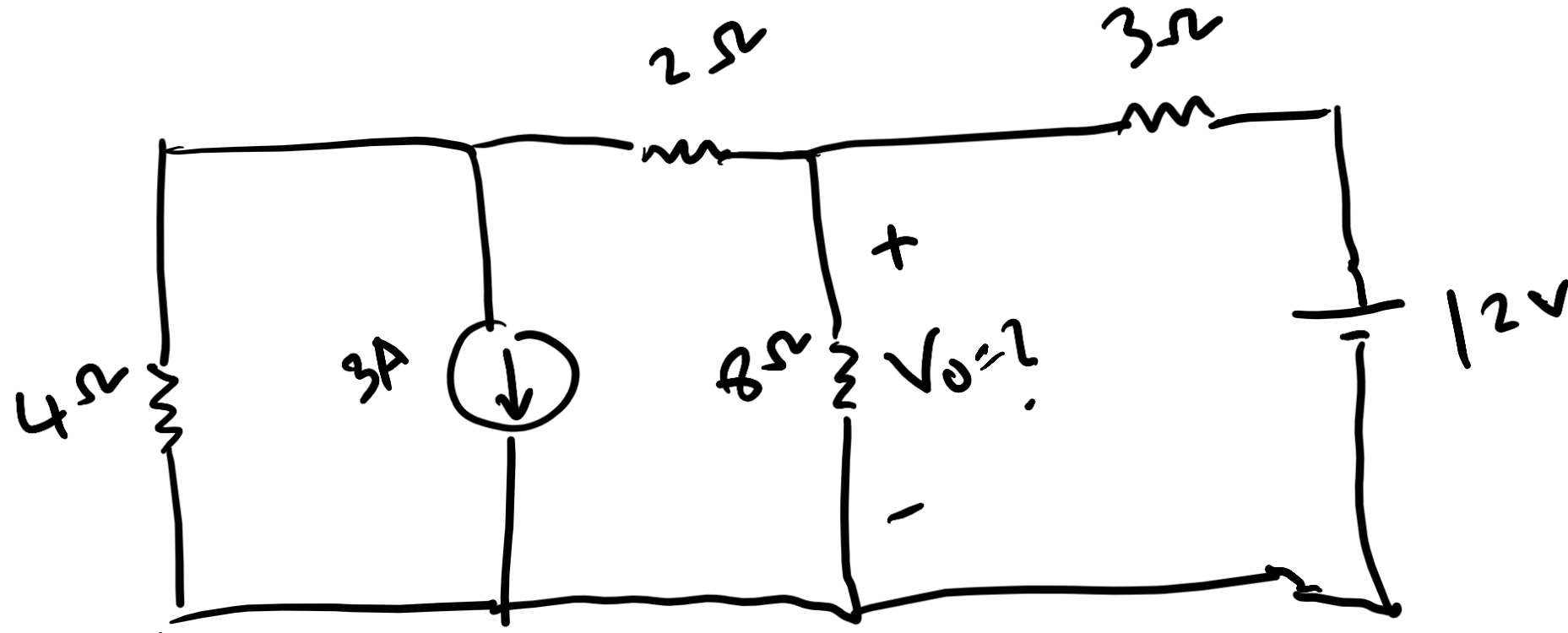
# Source transformation – Voltage $\leftrightarrow$ Current



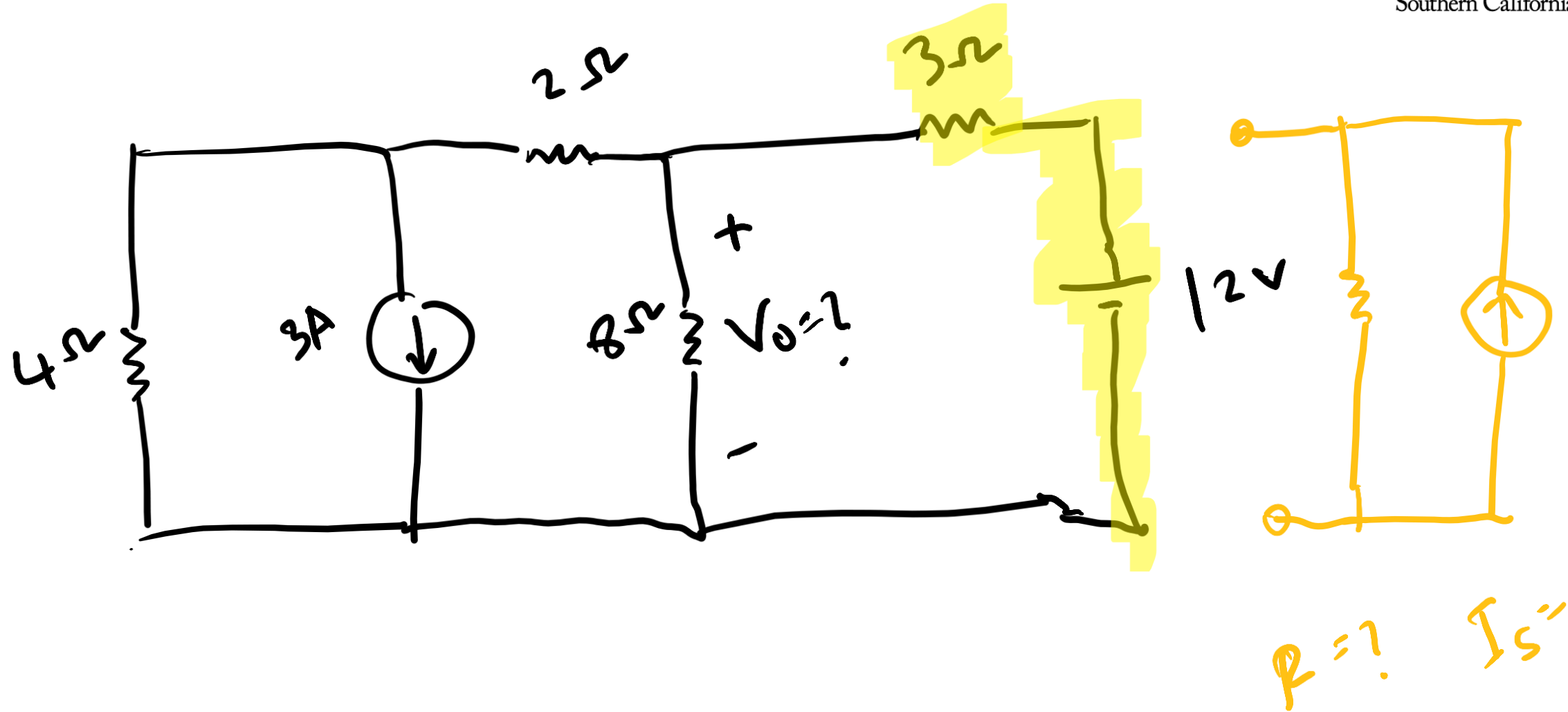
$$V_s = I_s R \Rightarrow$$

$$I_s = \frac{V_s}{R}$$

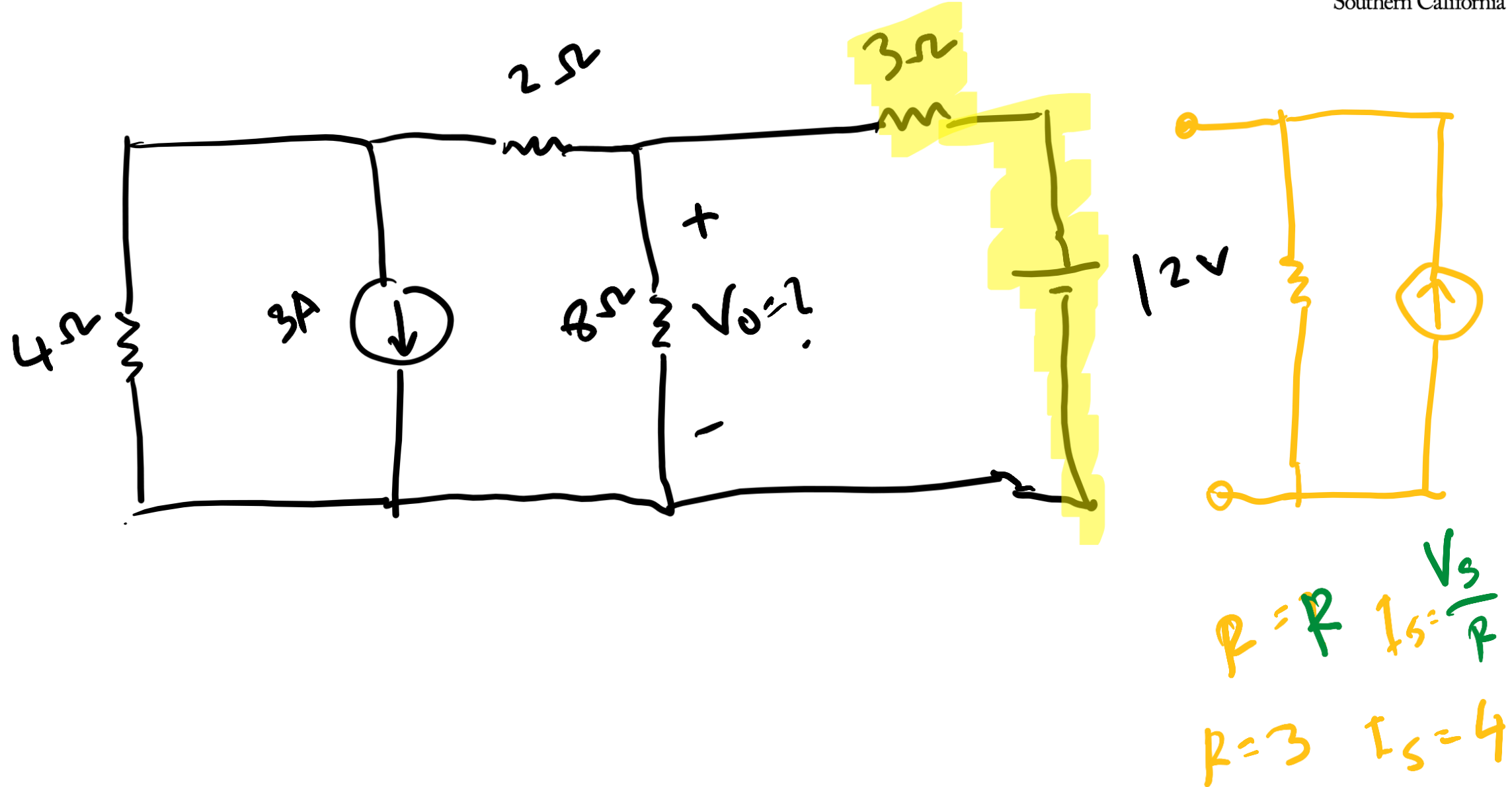
# Voltage transformation example



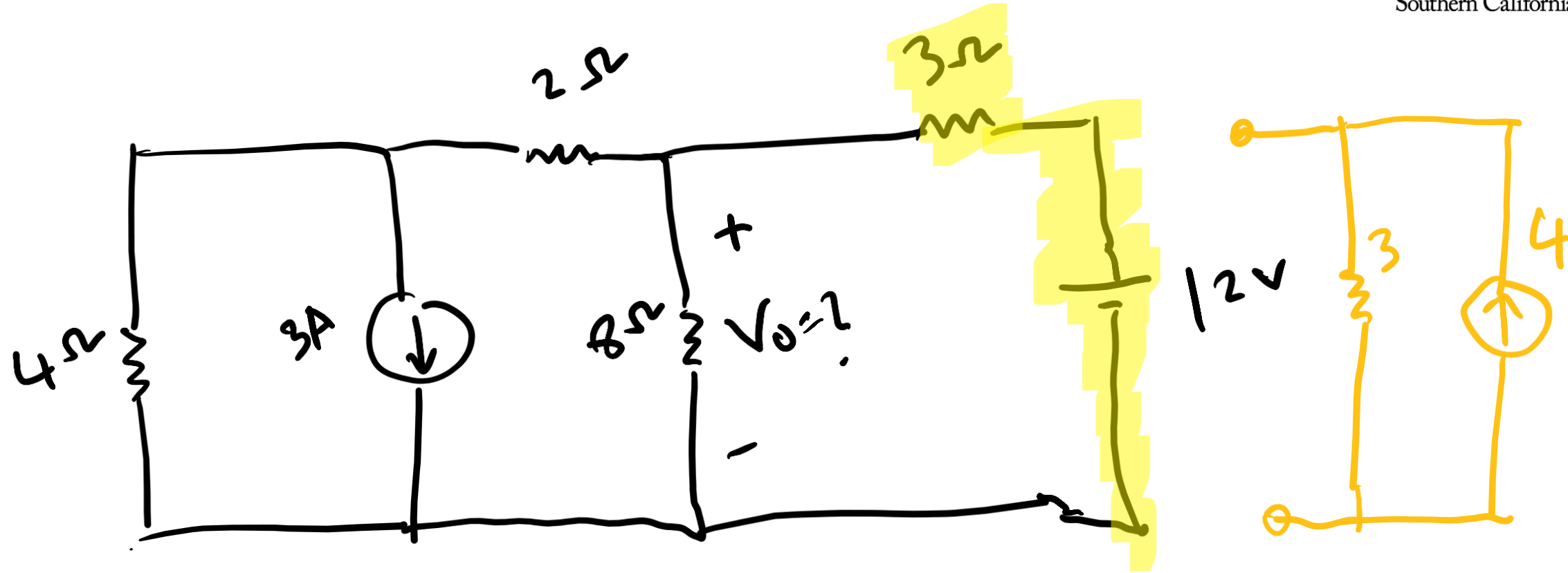
# Voltage transformation example



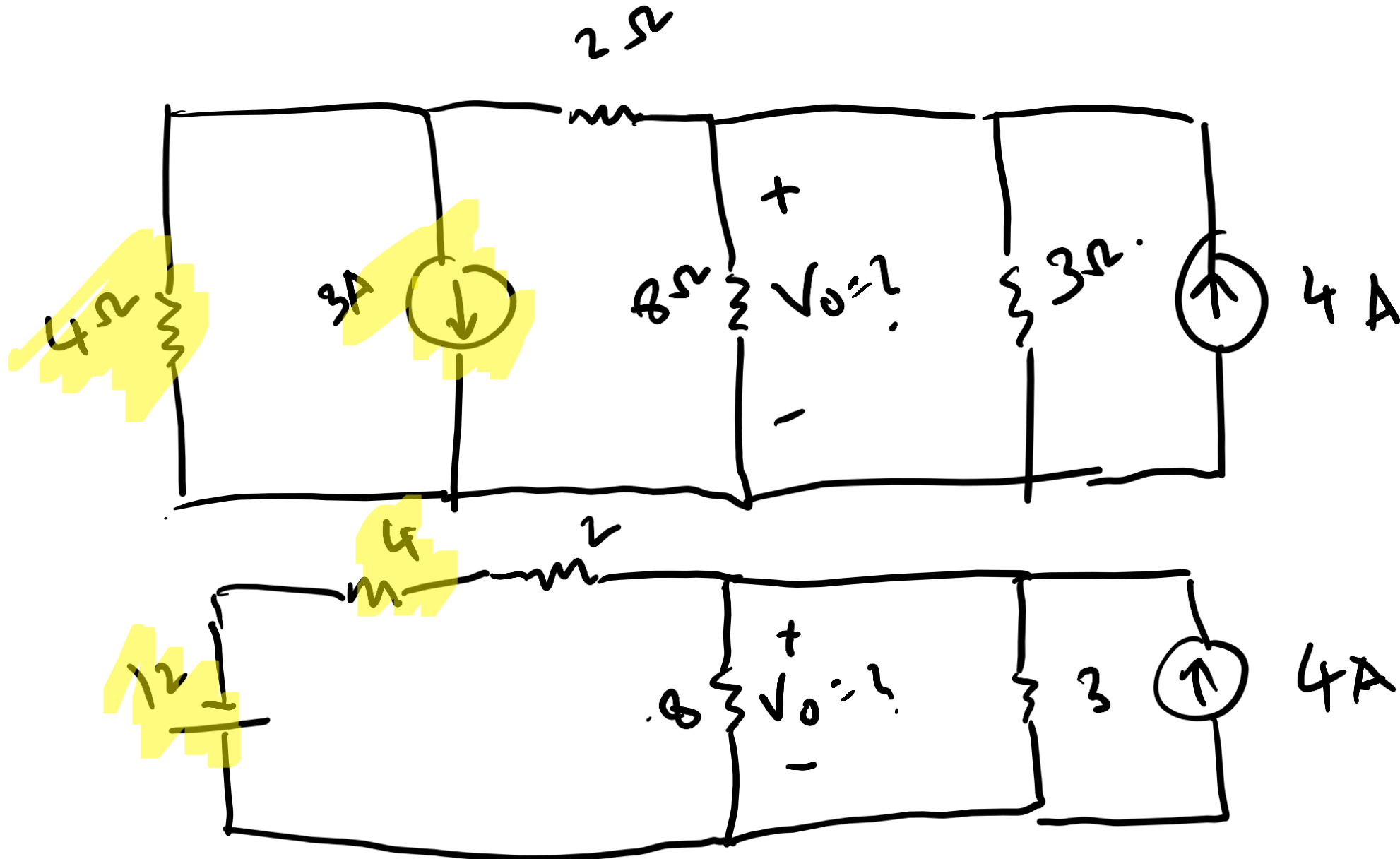
# Voltage transformation example



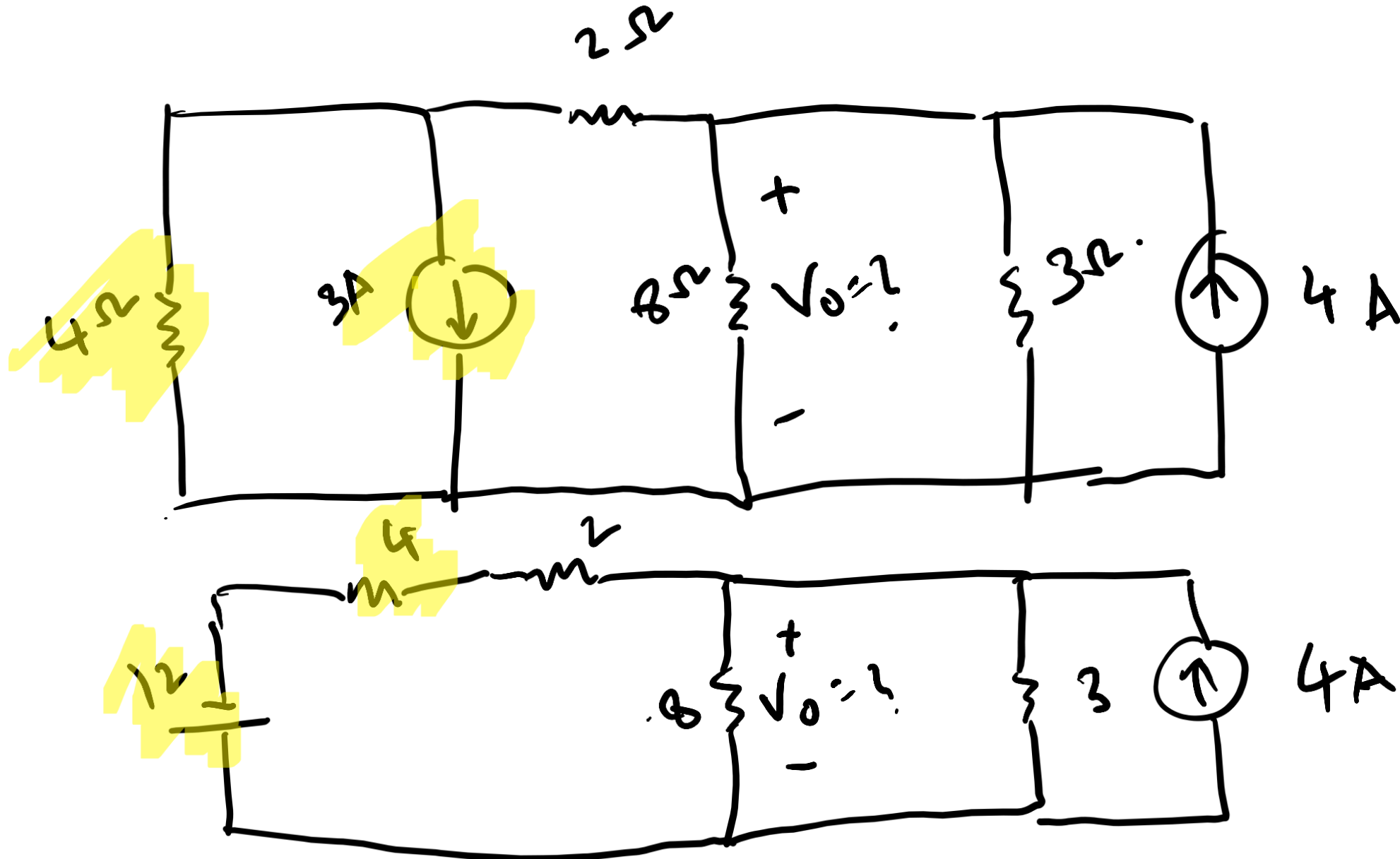
# Voltage transformation example



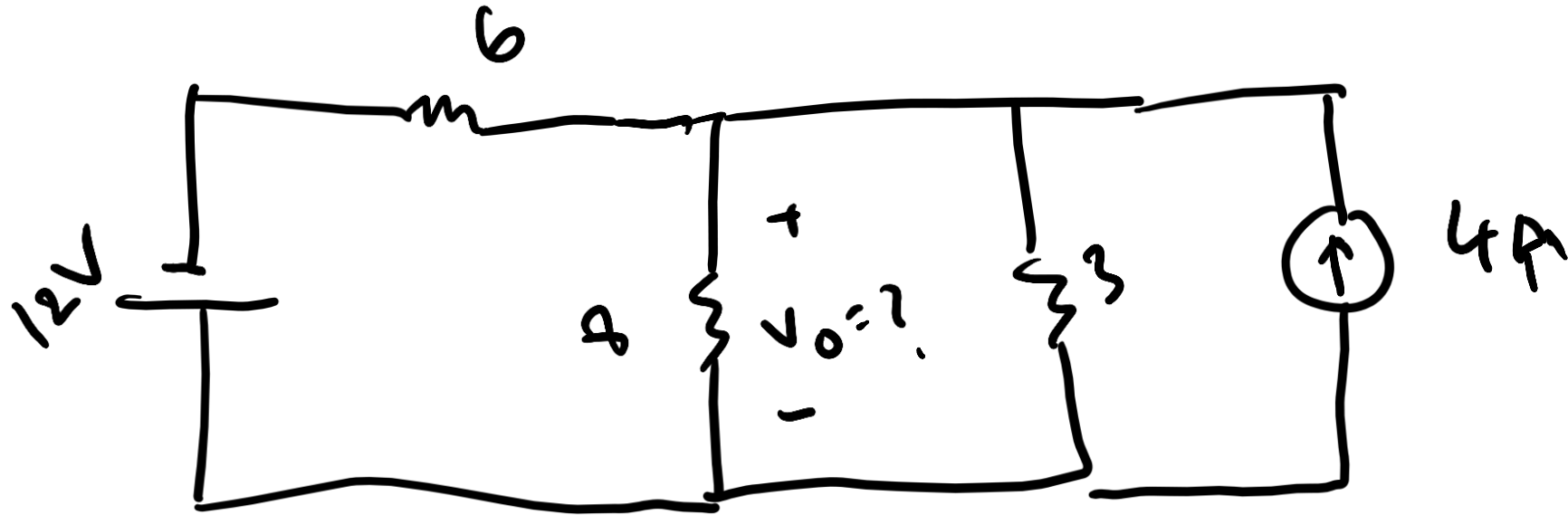
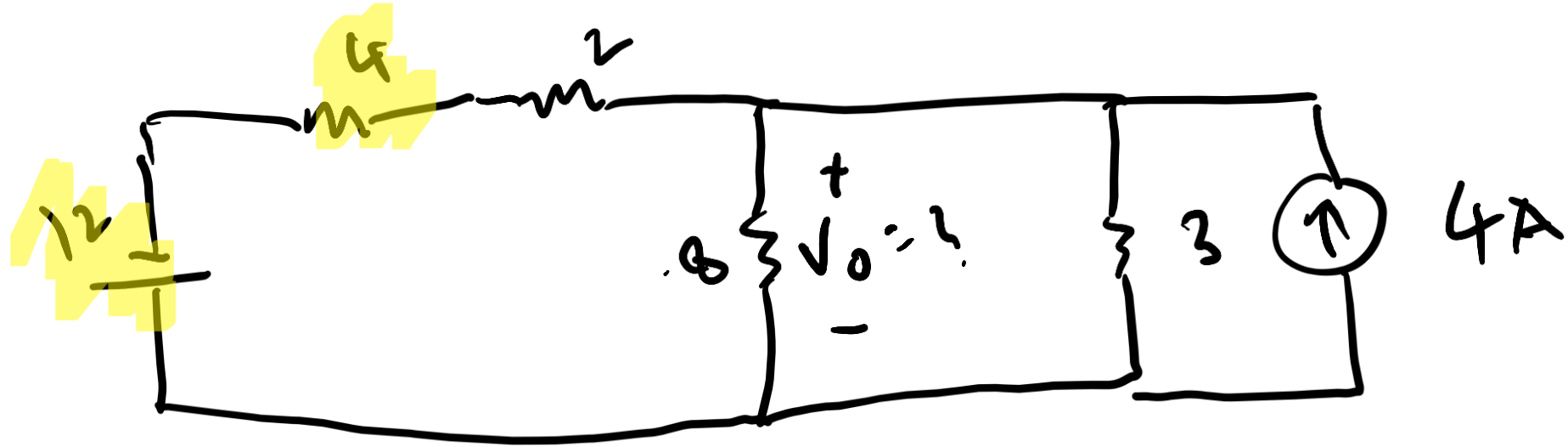
# Voltage transformation example



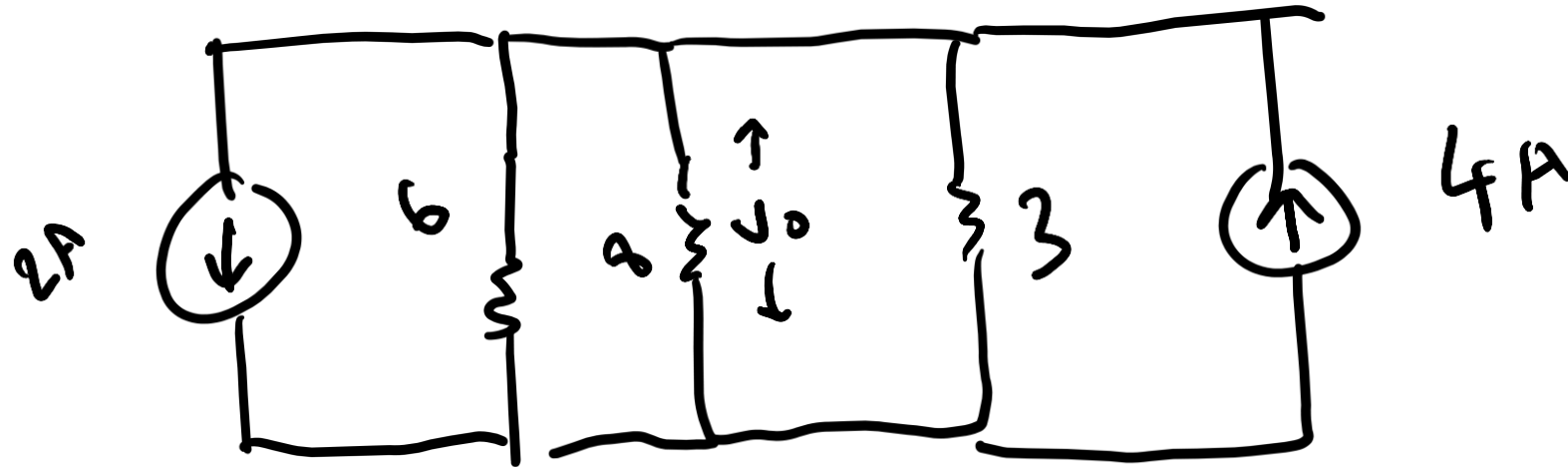
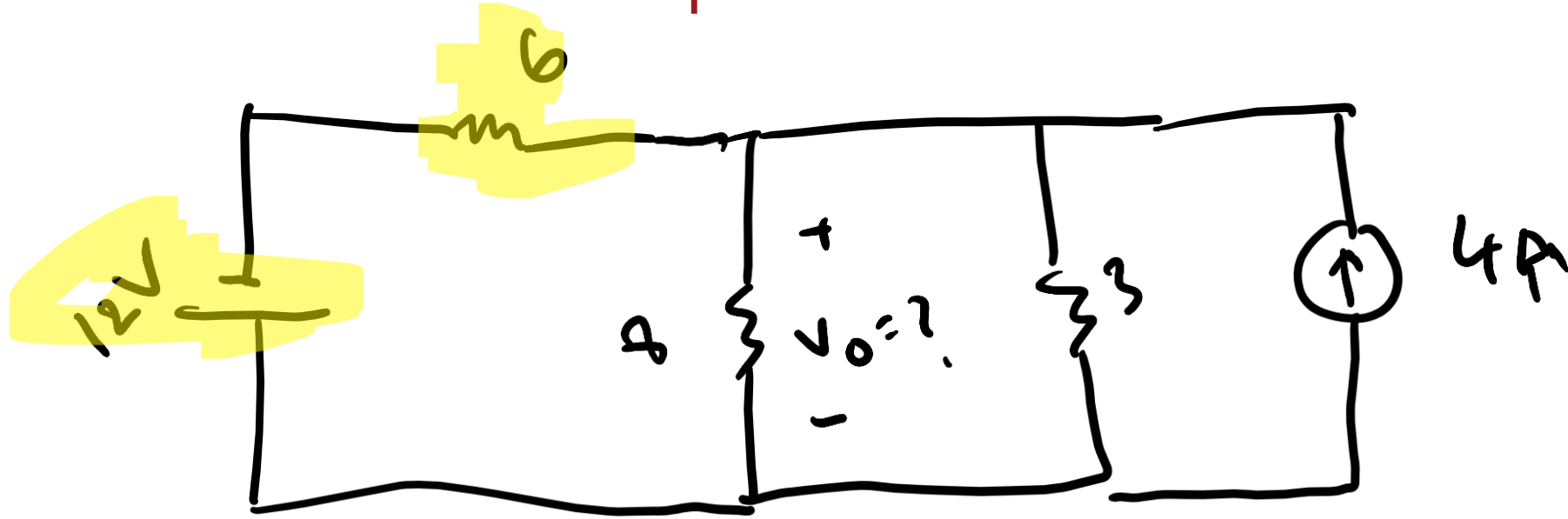
# Voltage transformation example



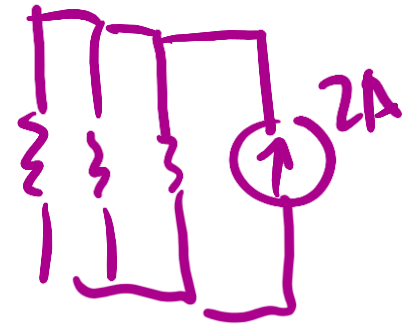
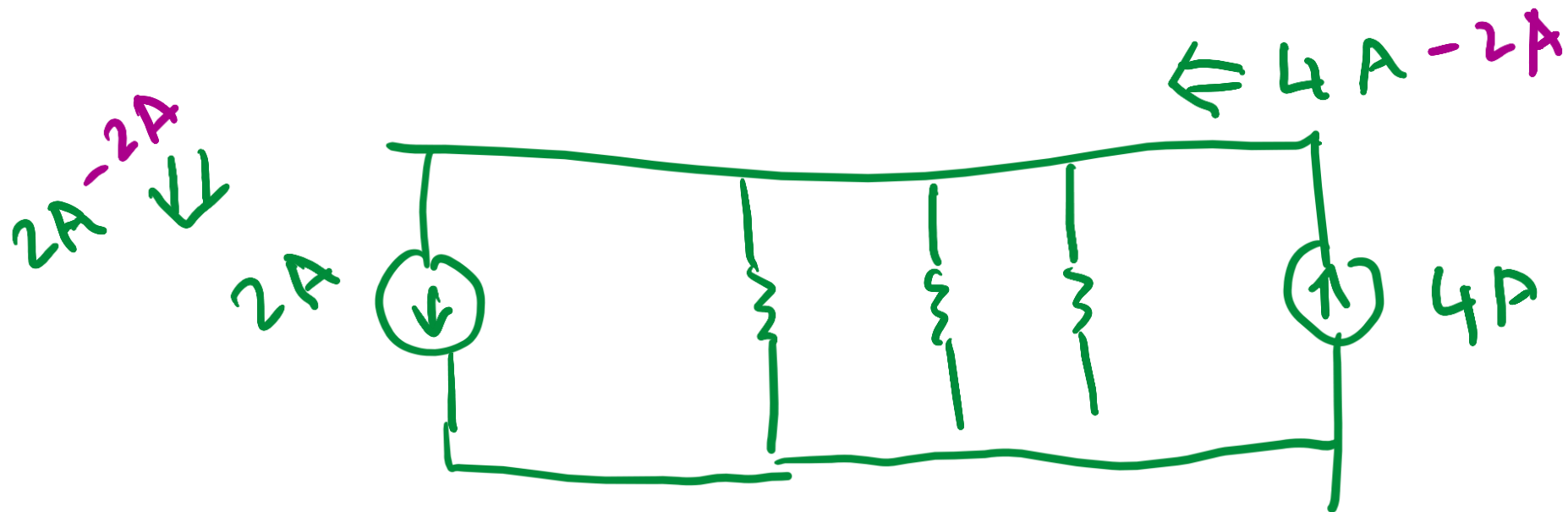
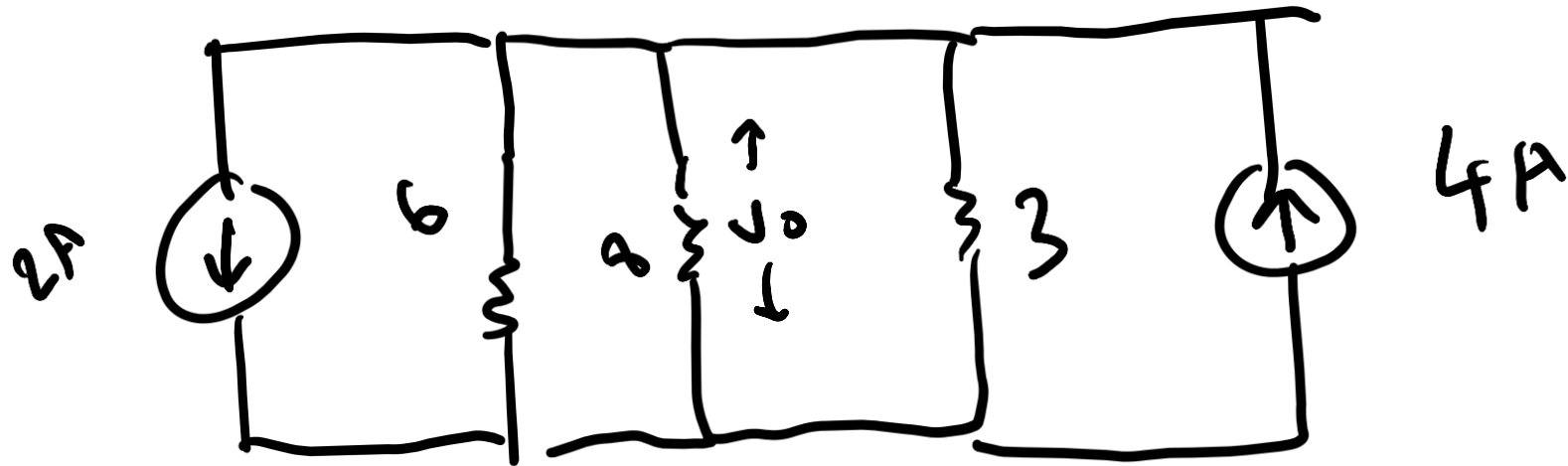
# Voltage transformation example



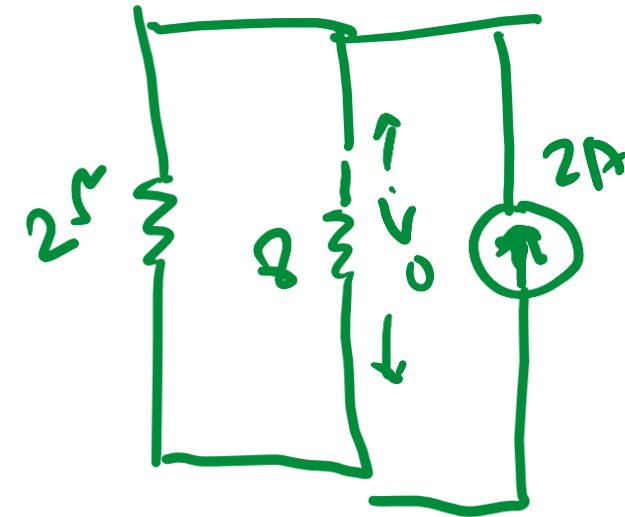
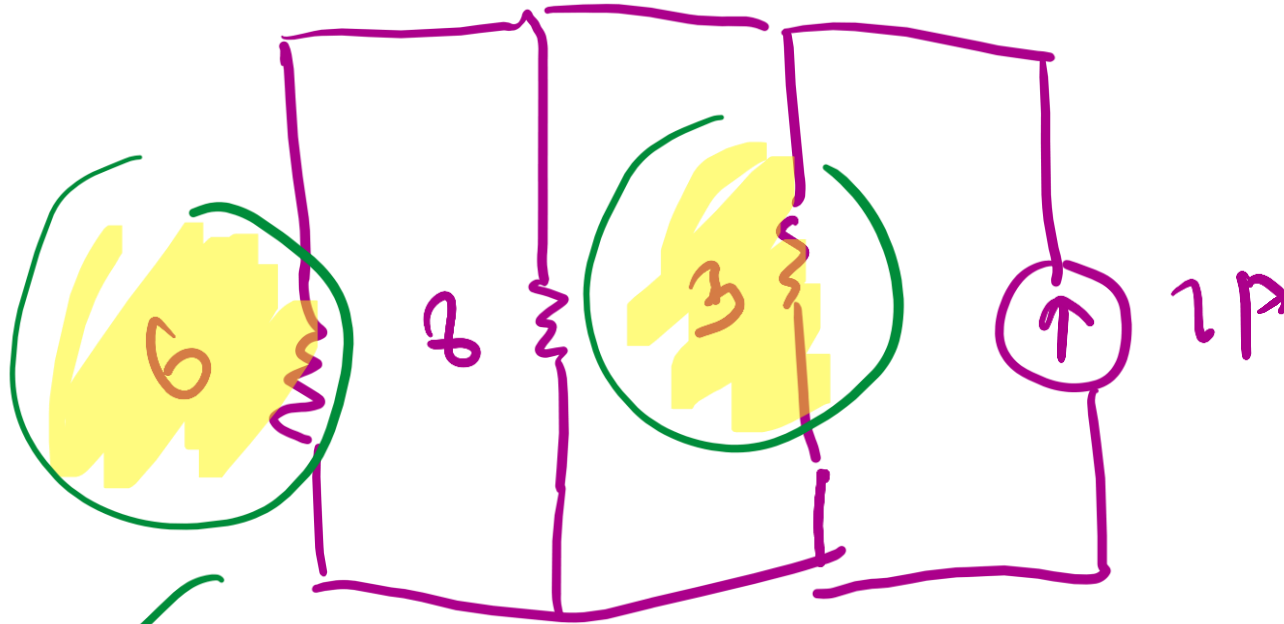
# Voltage transformation example



# Voltage transformation example

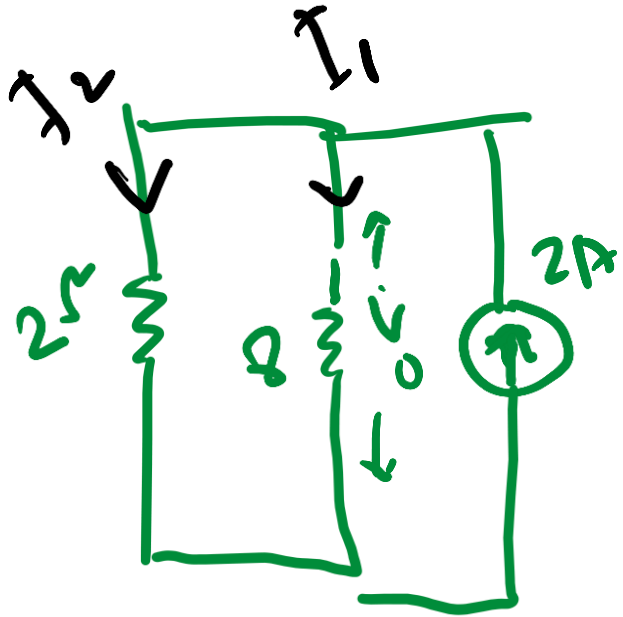


# Voltage transformation example



$$\rightarrow \frac{1}{R_{eq}} = \frac{1}{6} + \frac{1}{3} = \frac{9}{18} \Rightarrow R_{eq} = 2$$

# Voltage transformation example



$$I_1 = \frac{2 \times 2A}{10}$$

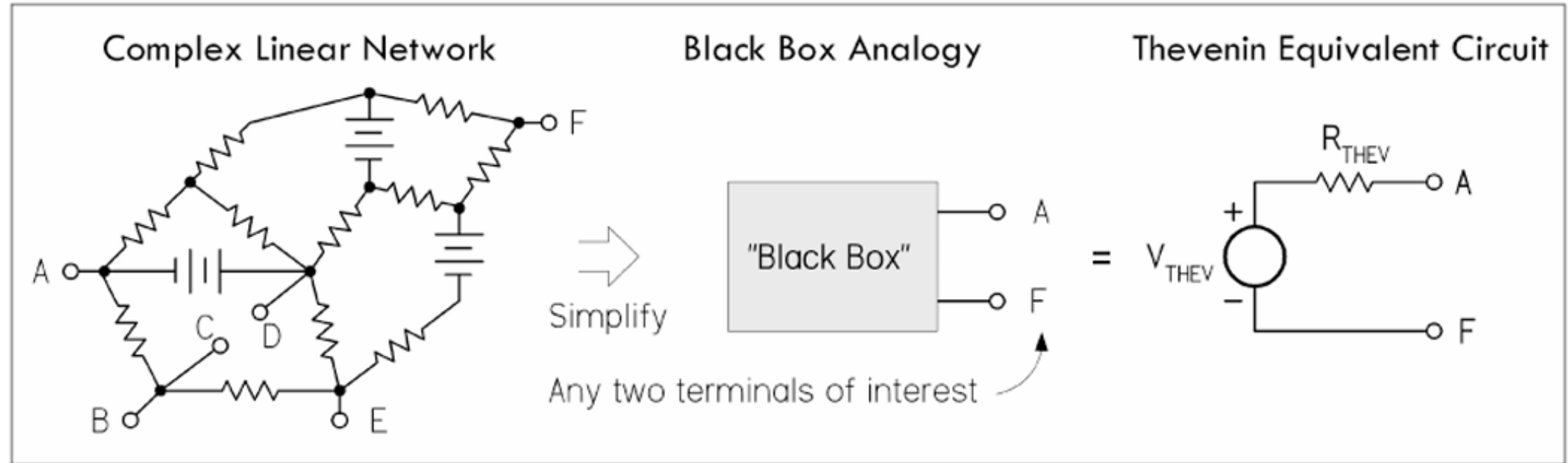
$$= .4A$$

$$V_0 = I_1 \cdot 8\Omega$$

$$= .4A \cdot 8\Omega$$

$$\boxed{= 3.2V}$$

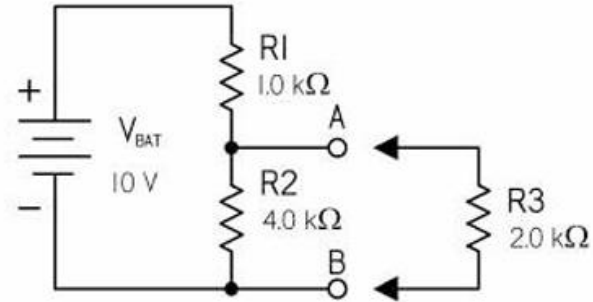
# Equivalent circuits



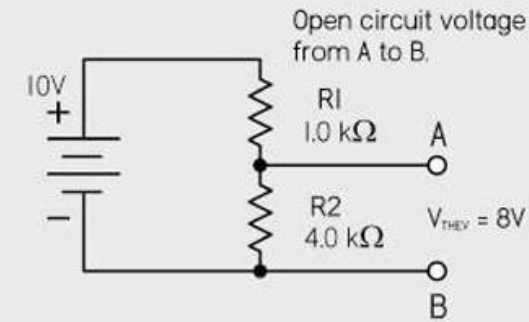
# Thevenin's equivalent circuit

## Thevenin's Theorem

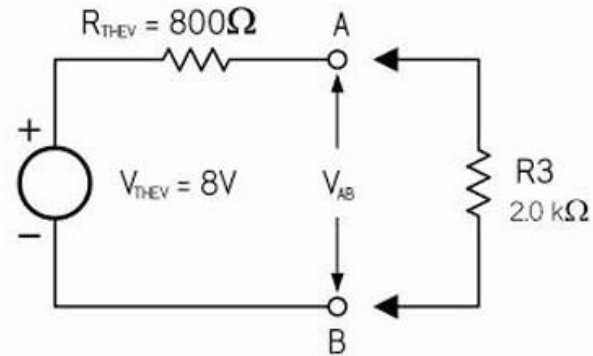
### Real Circuit



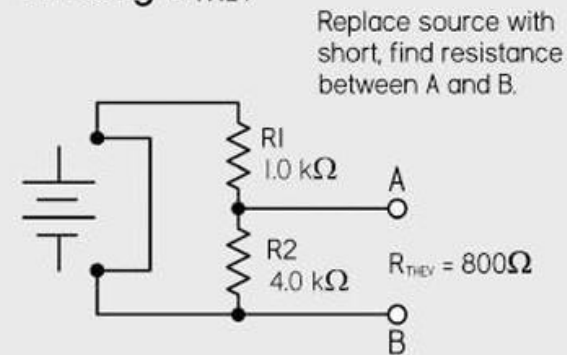
### Finding $V_{THEV}$



### Thevenin Equivalent Circuit



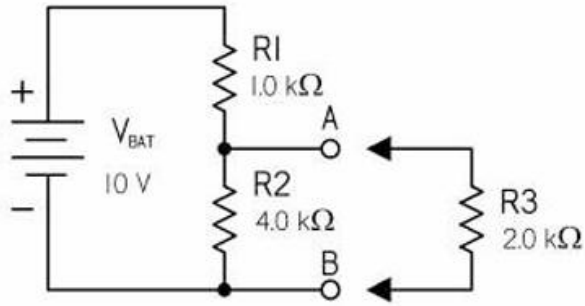
### Finding $R_{THEV}$



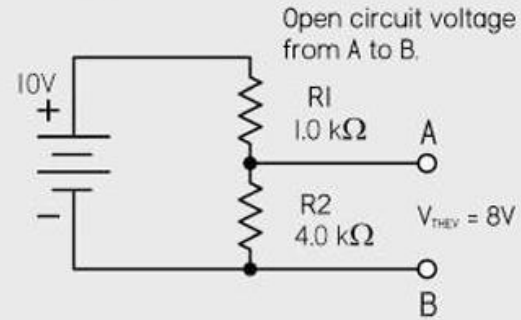
# Thevenin's equivalent circuit

## Thevenin's Theorem

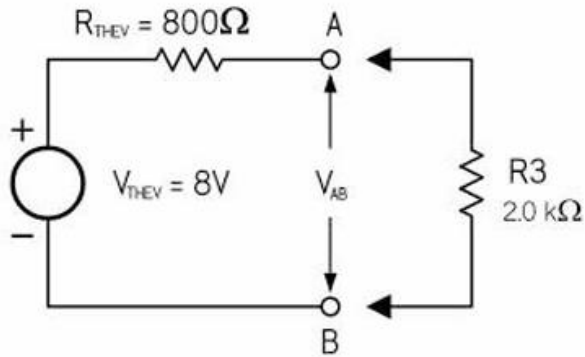
### Real Circuit



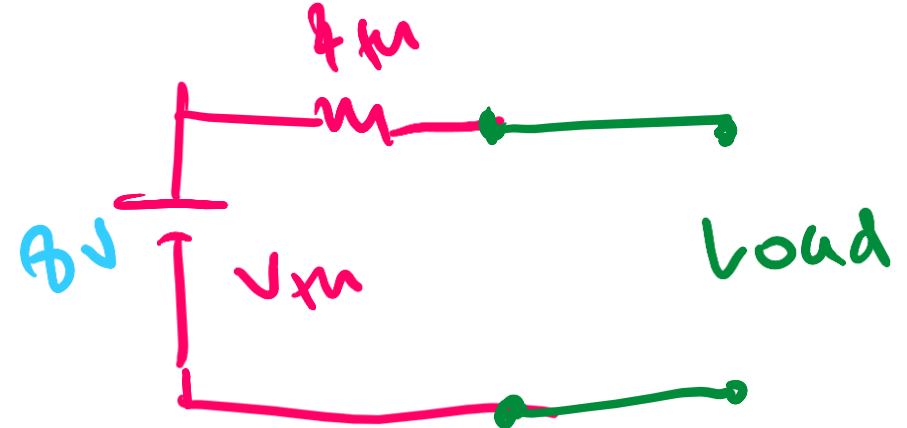
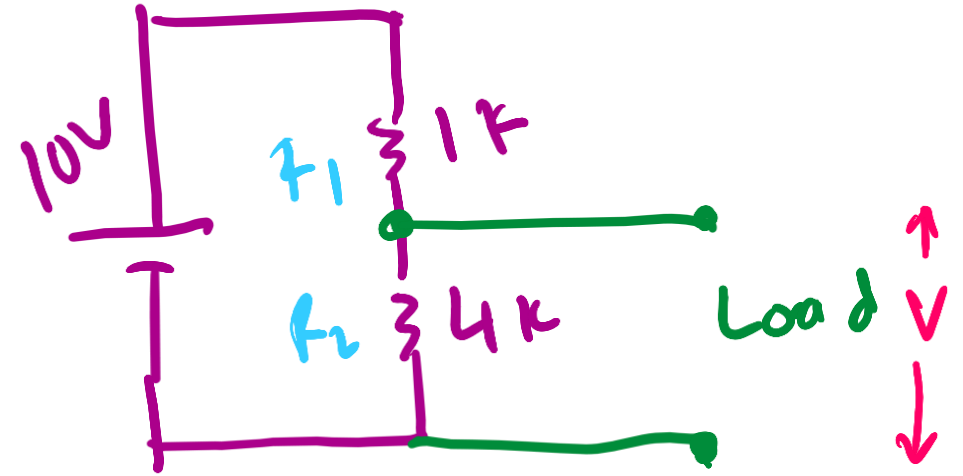
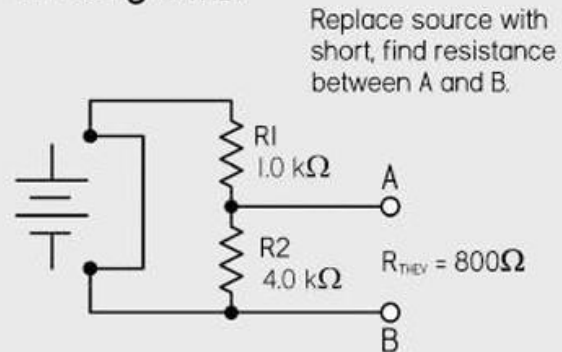
### Finding $V_{THEV}$



### Thevenin Equivalent Circuit

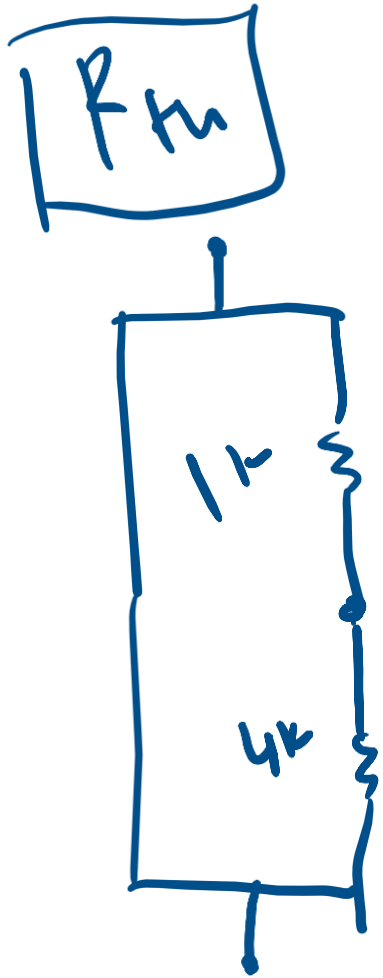


### Finding $R_{THEV}$



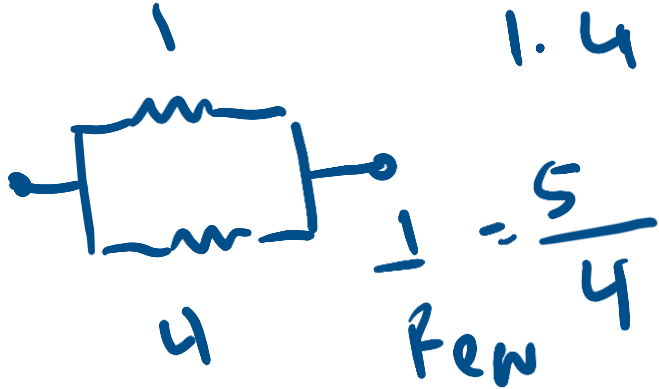
$$V_{THEV} = \frac{4 \cdot 10}{5} = 8V$$

# Thevenin's equivalent circuit

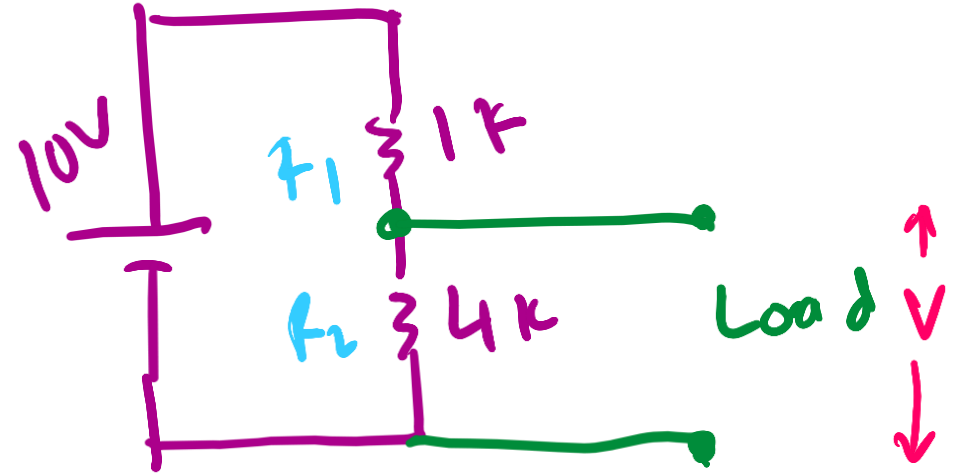


$$\frac{1}{R_{eq}} = \frac{1}{1k} + \frac{1}{4k}$$

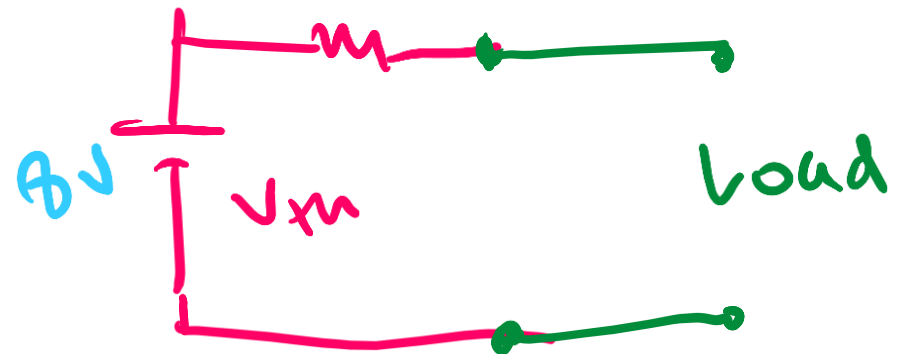
$$= \frac{5}{1.4}$$



$$R_{eq} = 800 \Omega$$



$$R_L = 800 \Omega$$

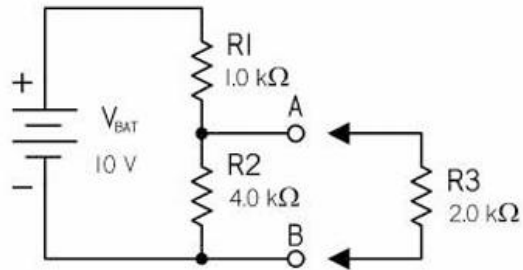


$$V_L = \frac{4 \cdot 10}{5} V = 8V$$

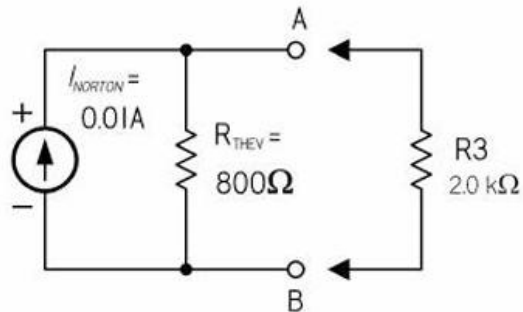
# Norton's equivalent circuit

## Norton's Theorem

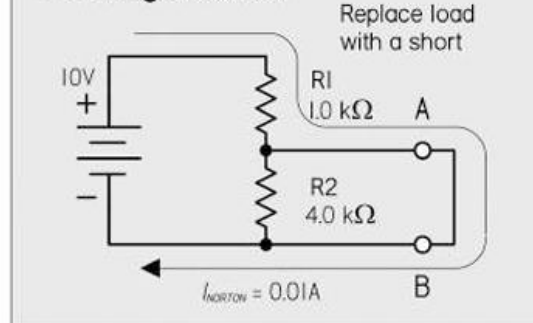
### Real Circuit



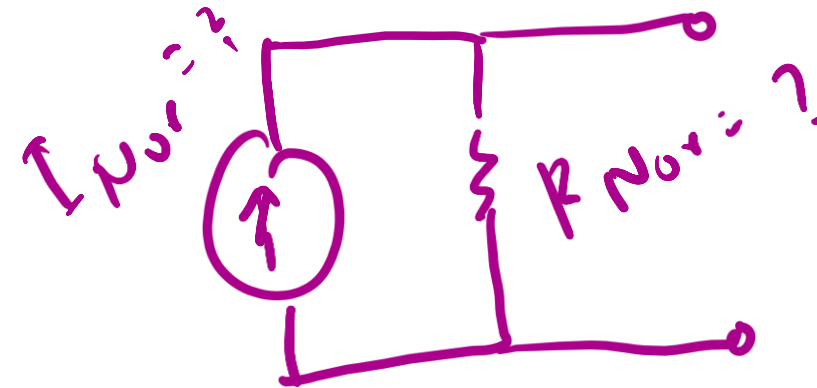
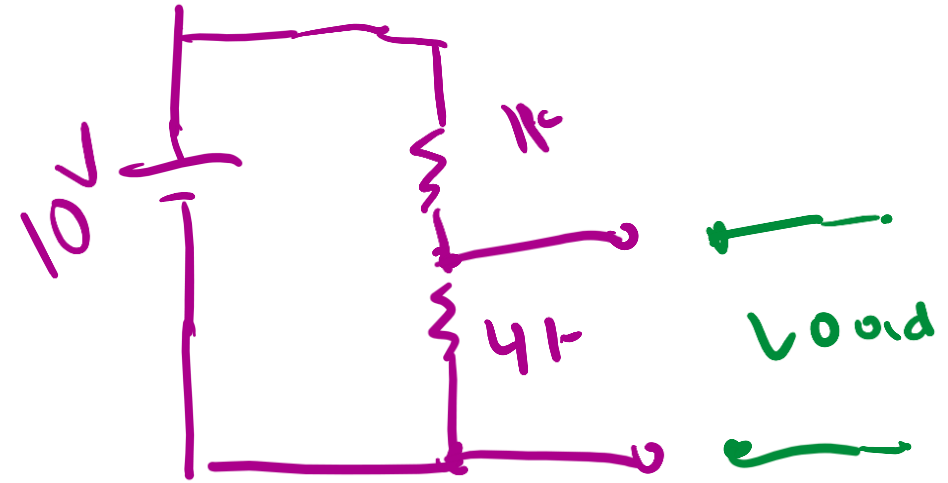
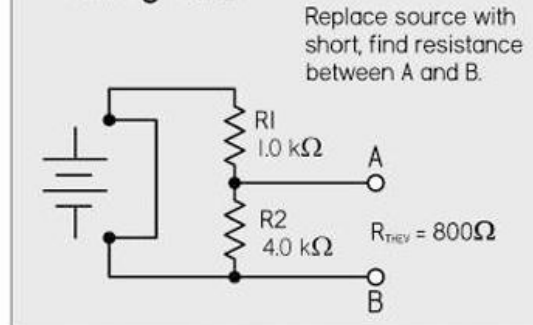
### Norton Equivalent Circuit



### Finding $I_{NORTON}$



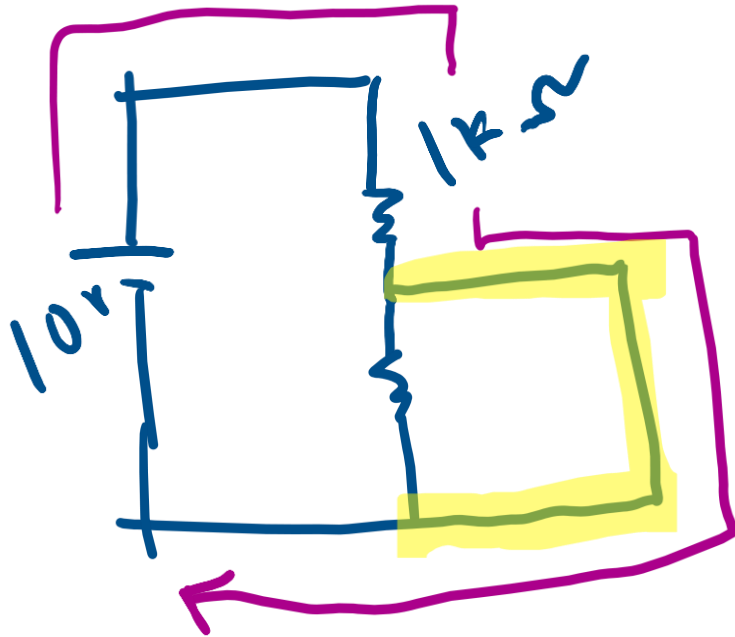
### Finding $R_{THEV}$



$$R_{Norton} = R_{TH} = 800 \Omega$$

# Norton's equivalent circuit

Replace load with a  
Short.

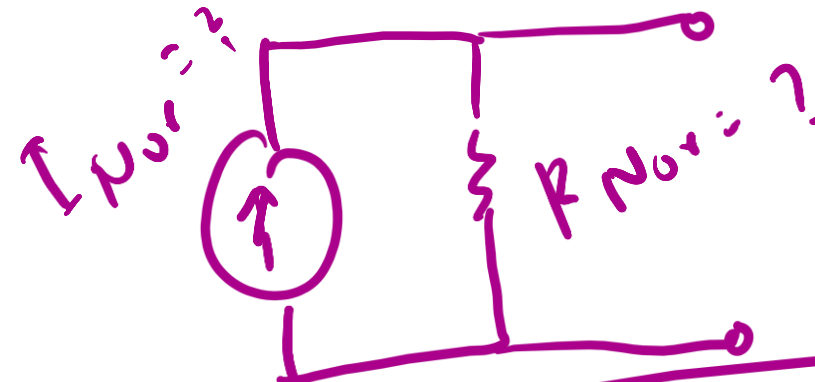
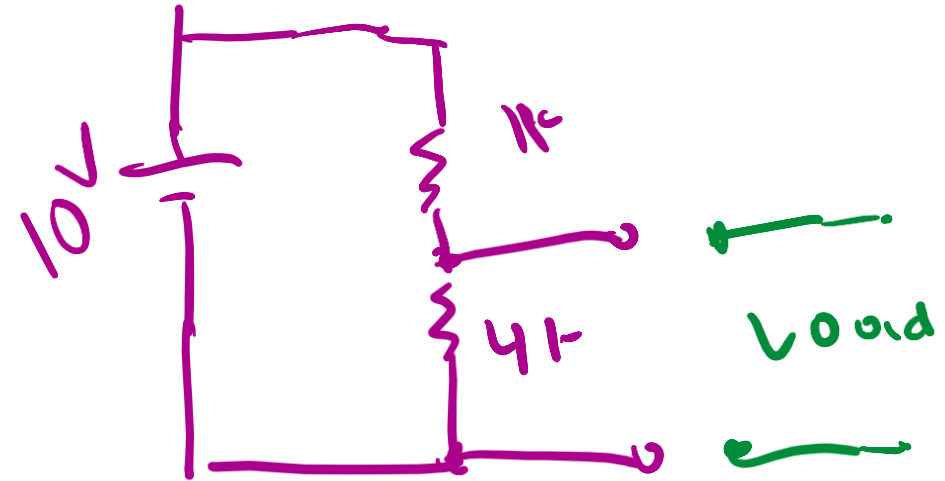


$$V = IR$$

$$I = \frac{V}{R} = \frac{10V}{1k}$$

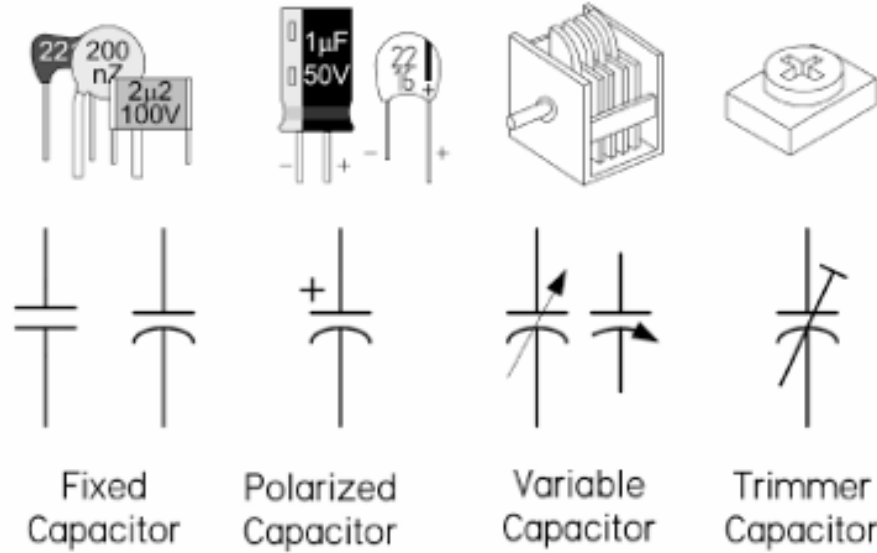
$$= 0.01 A$$

$$I_{NOR} = 0.01 A$$

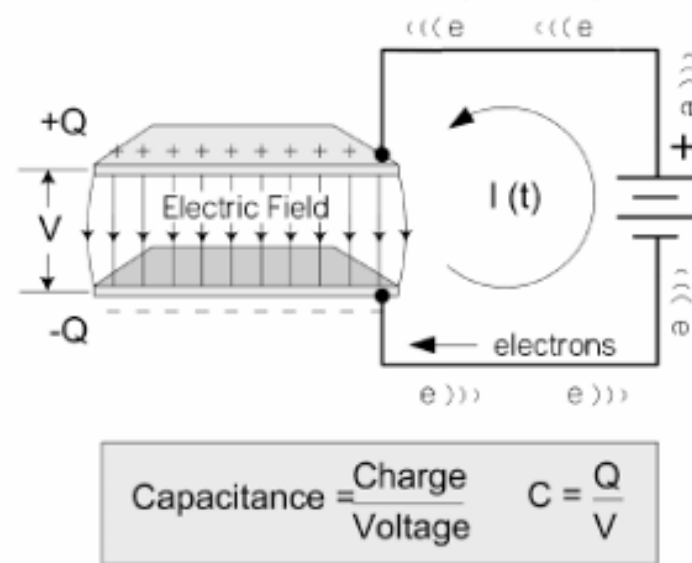


$$R_{NOR} = R_{TH} = 800 \Omega$$

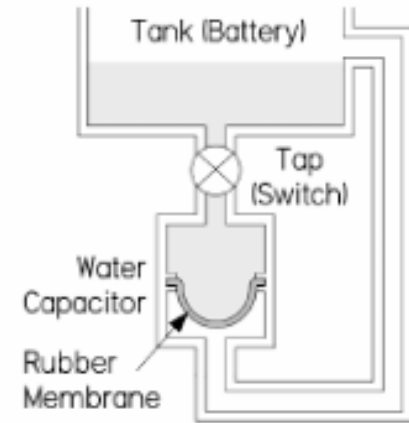
## Capacitor Symbols



## Parallel Plate Capacitor

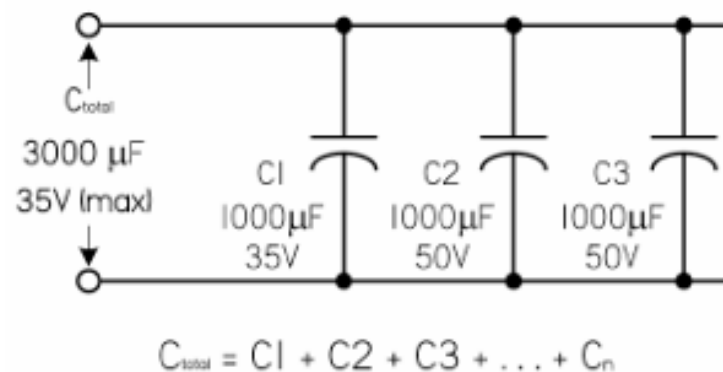


## Water Analogy



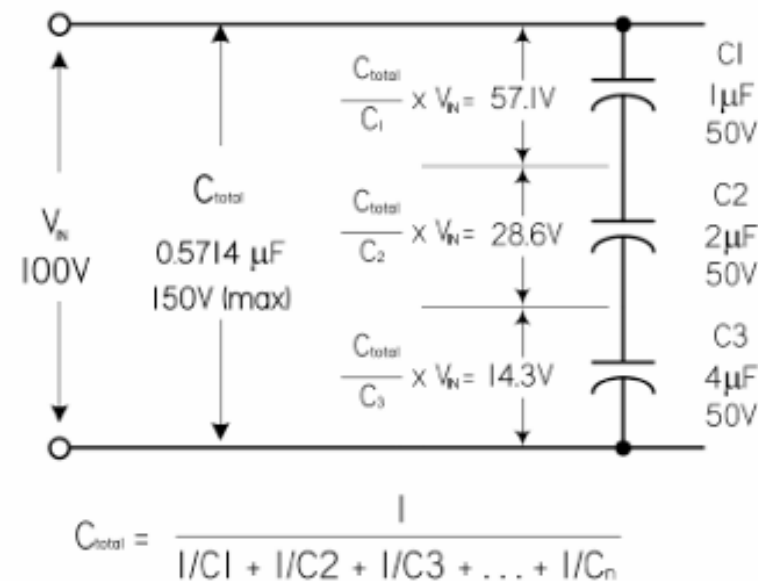
## Capacitors In Parallel

Increases the total capacitance, but limits max. voltage rating to that of smallest rated capacitor.



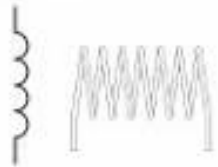
## Capacitors In Series

Increases max voltage rating, but decreases capacitance.

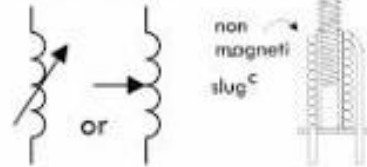


## Inductor Symbols

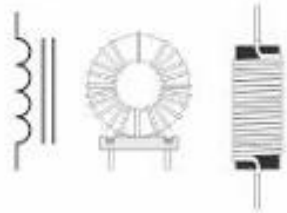
Air Core



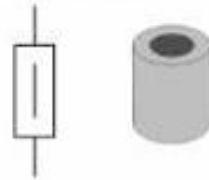
Adjustable



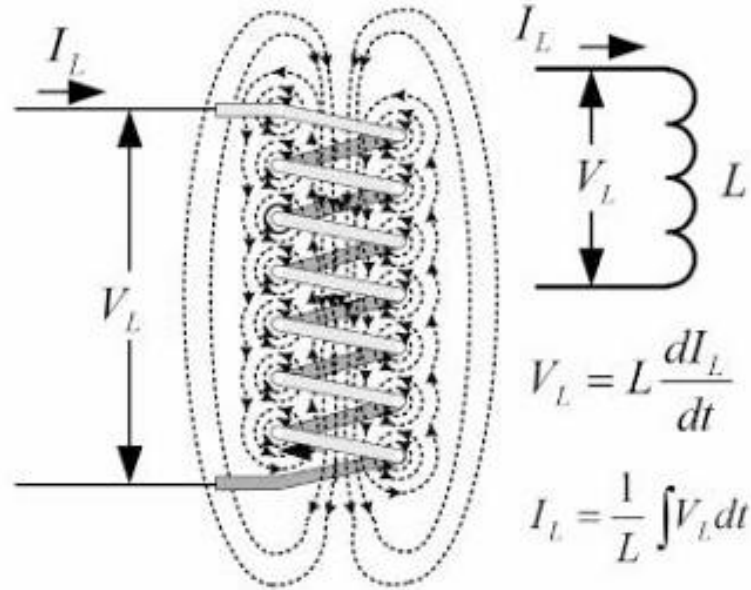
Magnetic or Iron Core



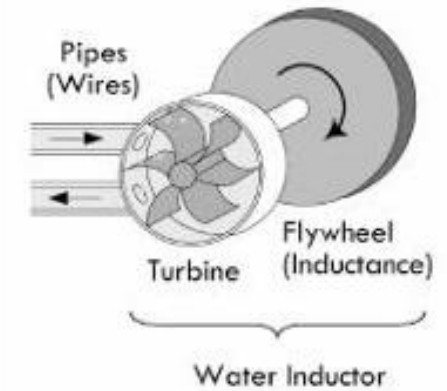
Ferrite Bead



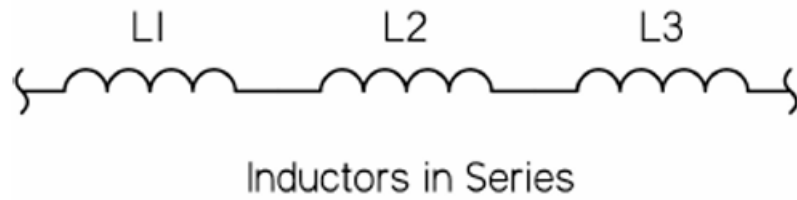
## Air-Core Inductor



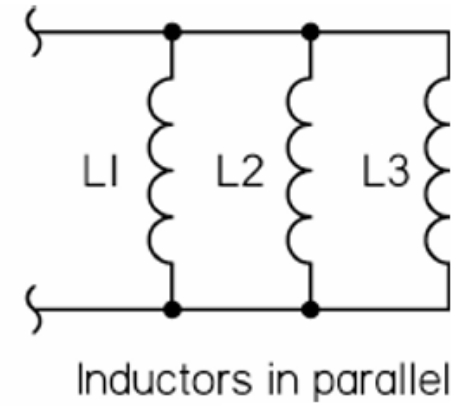
## Water Analogy



# Inductors

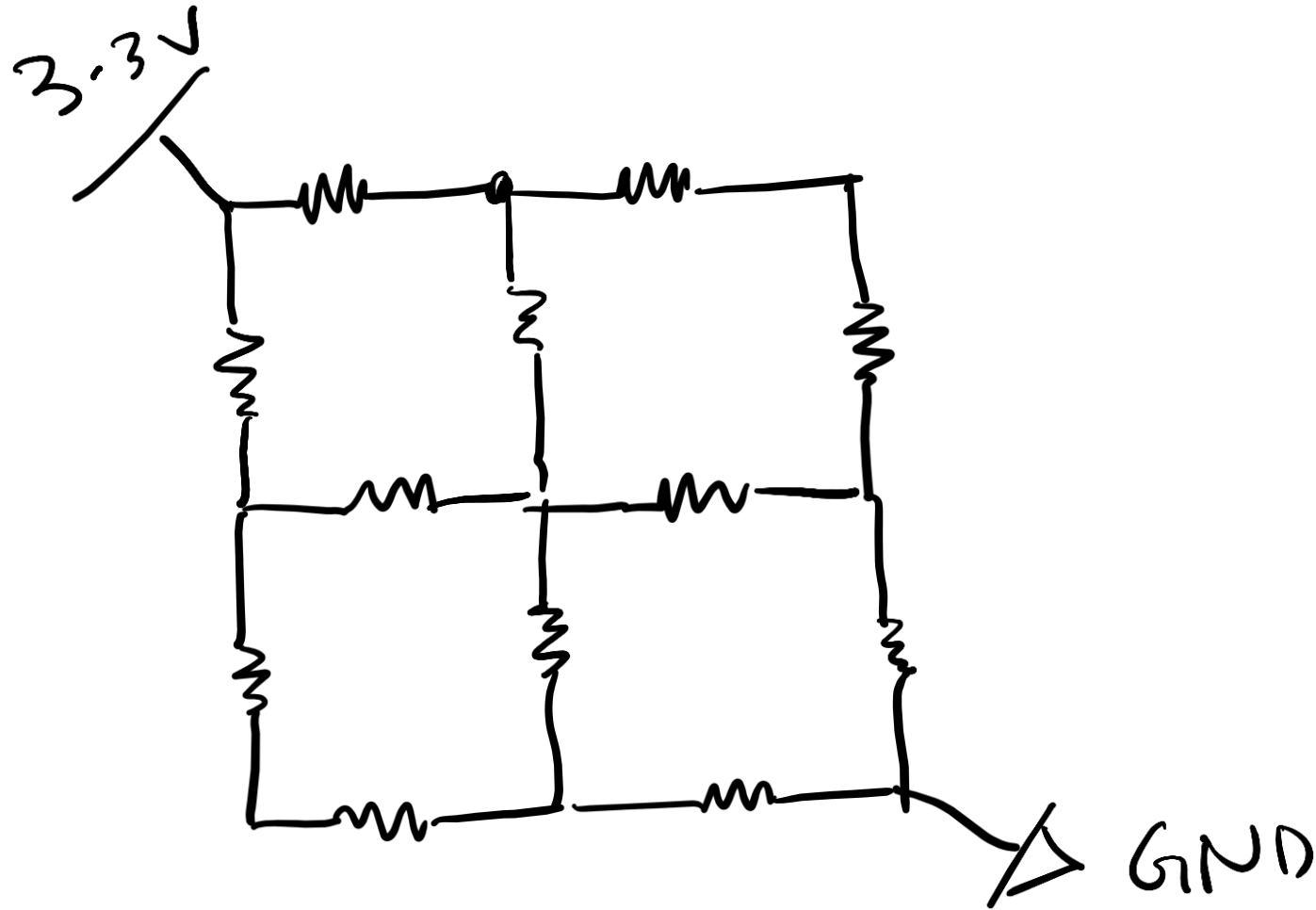


$$L_{\text{eq}} = L_1 + L_2 + L_3$$

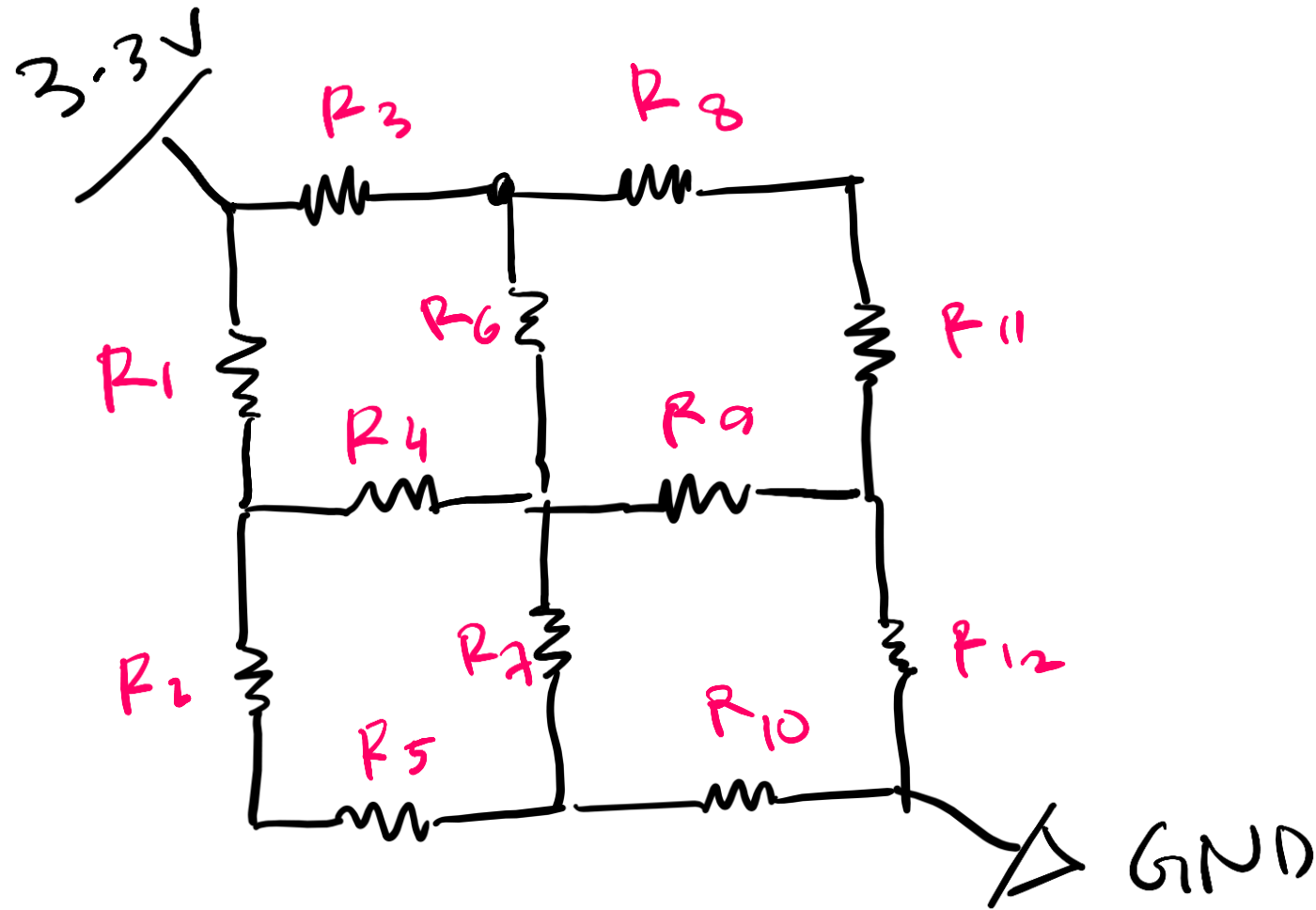


$$\frac{1}{L_{\text{eq}}} = \frac{1}{L_1} + \frac{1}{L_2} + \frac{1}{L_3}$$

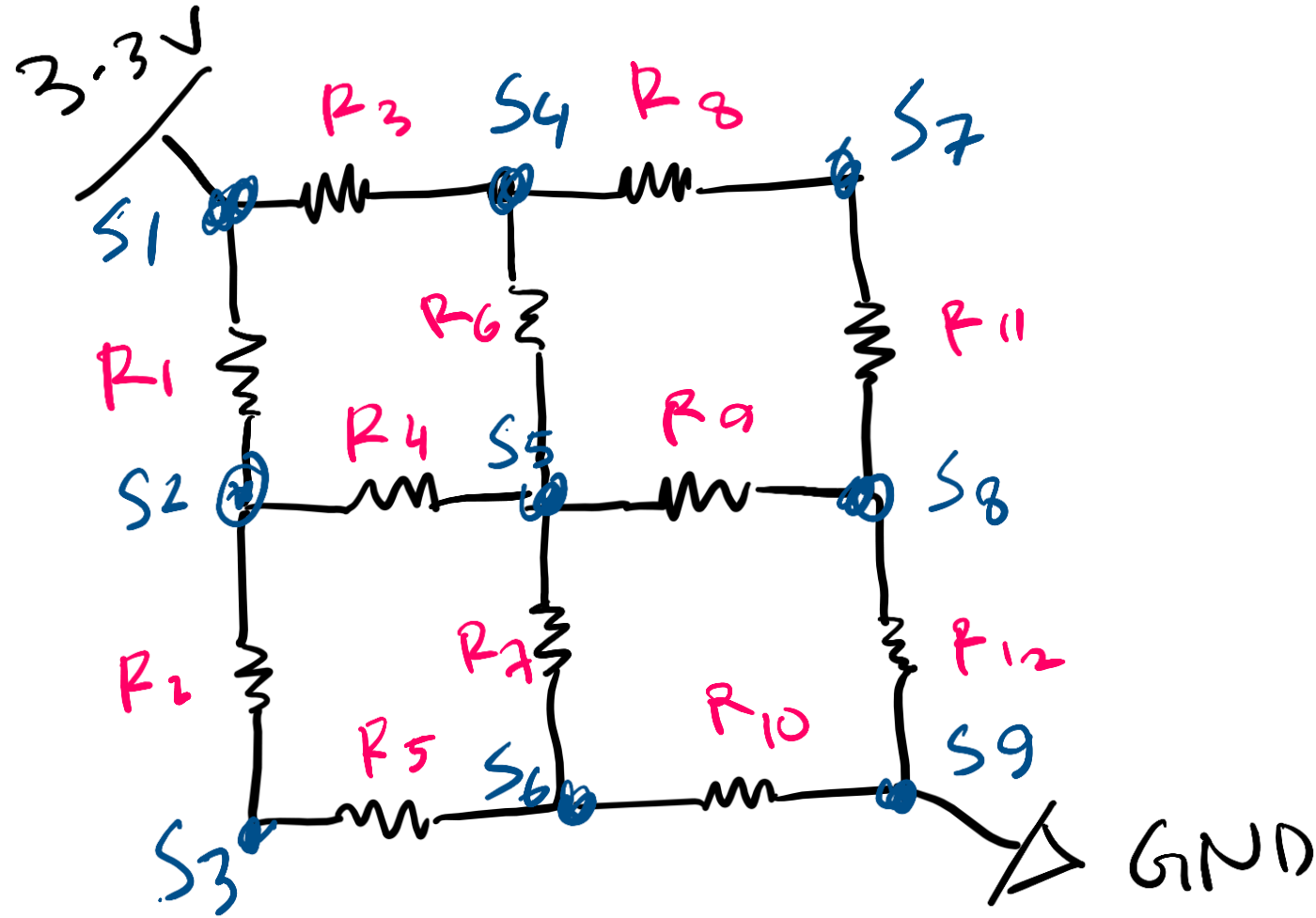
# Touchpad – Network 2 in the demo board



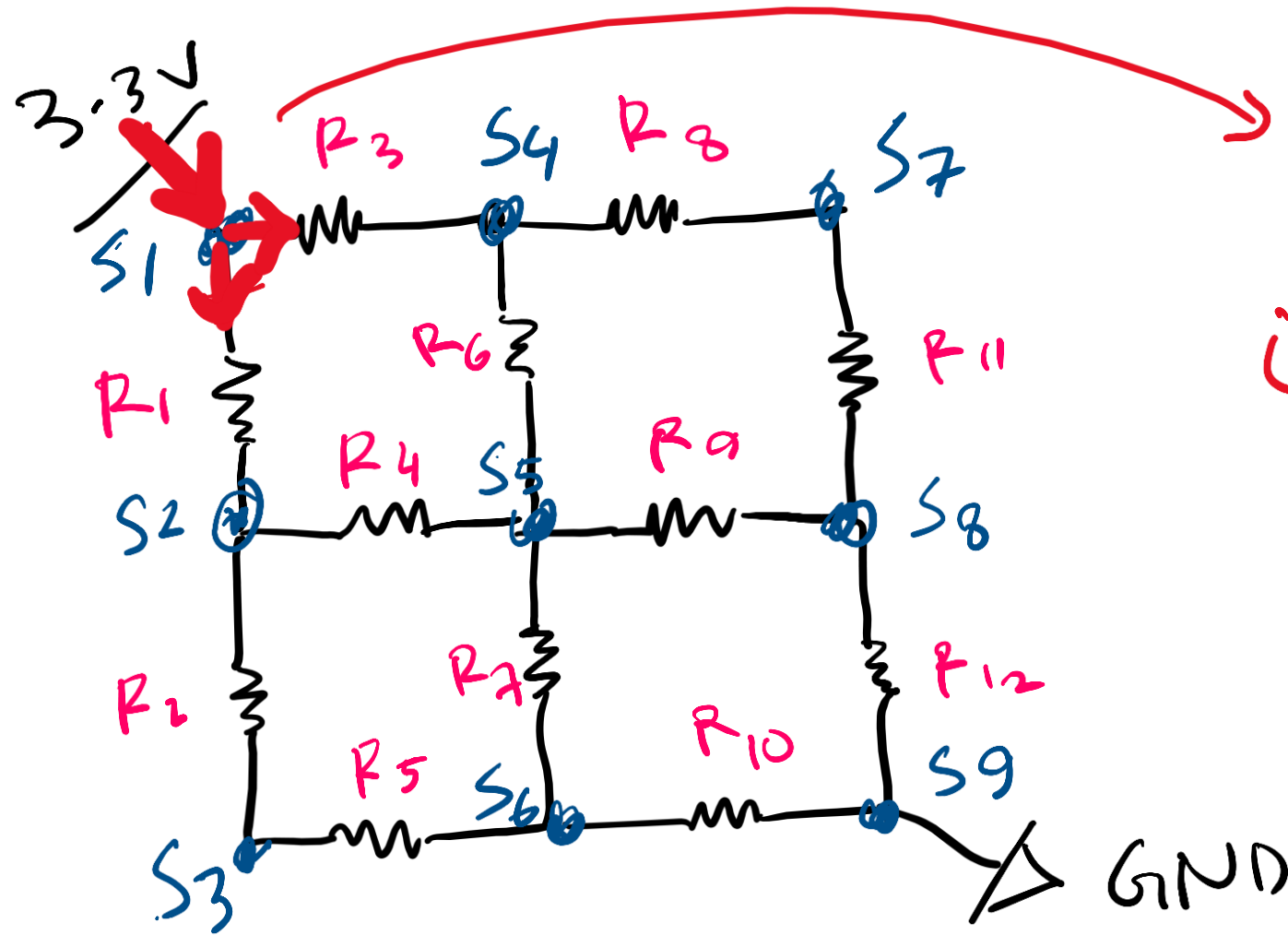
# Touchpad – Network 2 in the demo board



# Touchpad – Network 2 in the demo board



# Touchpad – Network 2 in the demo board



$$i_{tot} = i_{R1} + i_{R3}$$

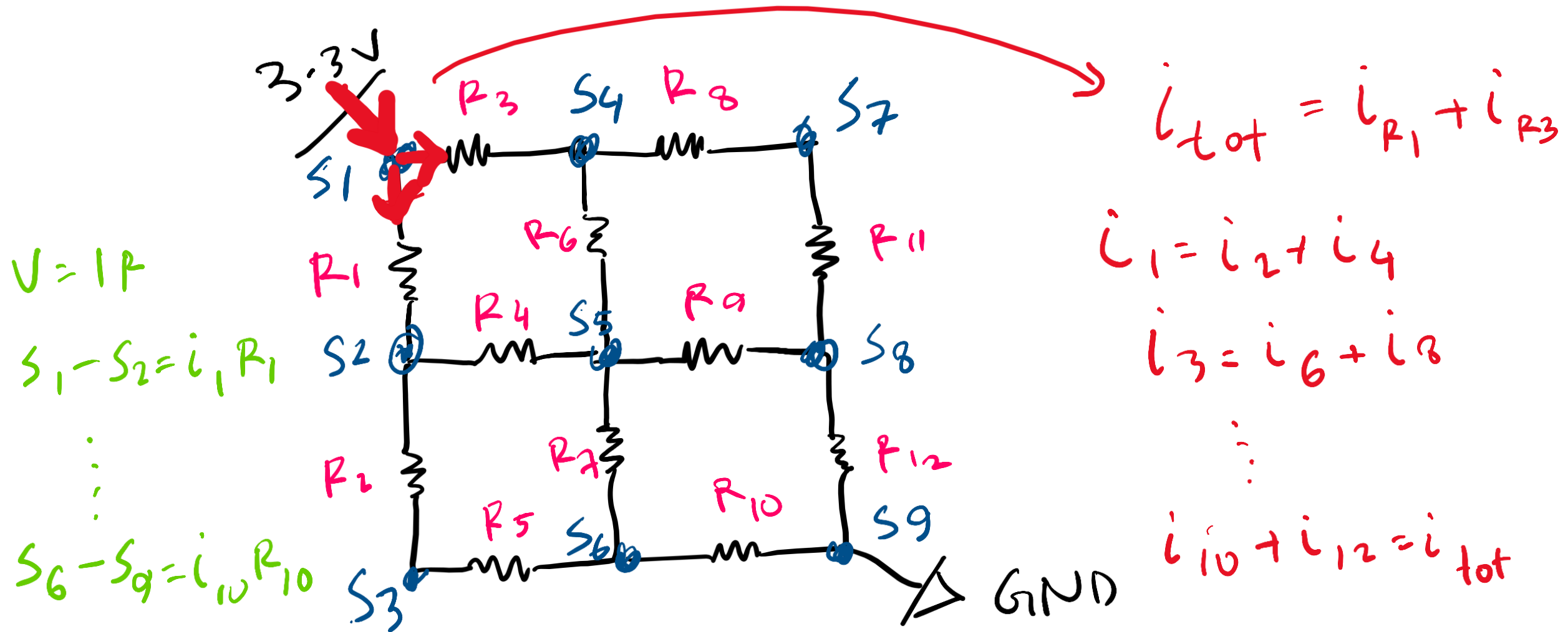
$$i_1 = i_2 + i_4$$

$$i_3 = i_6 + i_8$$

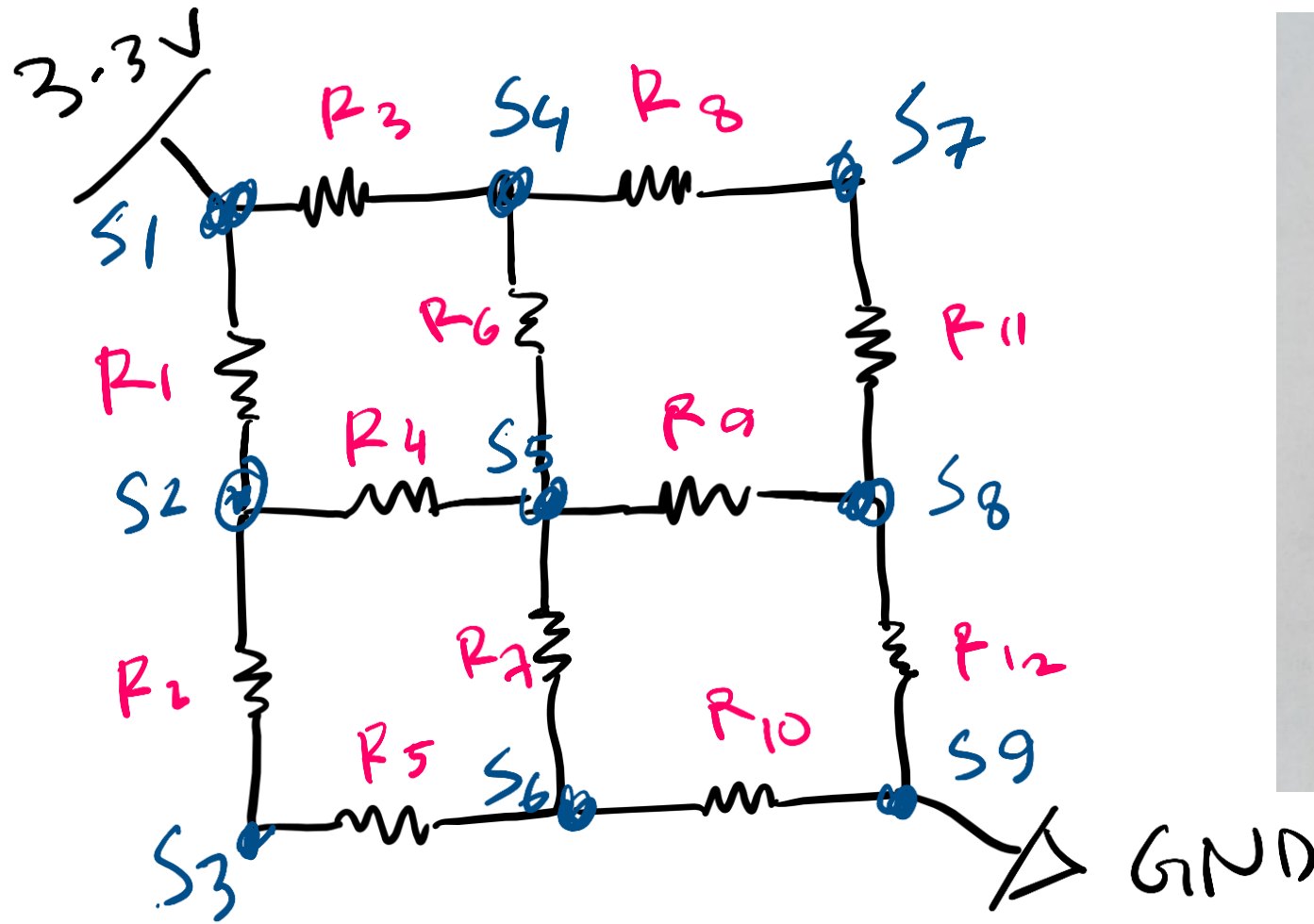
$\vdots$

$$i_{10} + i_{12} = i_{tot}$$

# Touchpad – Network 2 in the demo board



# Touchpad – Network 2 in the demo board



$$\begin{aligned}
 I_t &= i_{R1} + i_{R3} \\
 i_{R1} &= i_{R2} + i_{R4} \\
 i_{R3} &= i_{R6} + i_{R8} \\
 i_{R2} &= i_{R5} \\
 i_{R8} &= i_{R11} \\
 i_{R4} + i_{R6} &= i_{R7} + i_{R9} \\
 i_{R5} + i_{R7} &= i_{R10} \\
 i_{R9} + i_{R11} &= i_{R12} \\
 i_{R10} + i_{R12} &= I_t
 \end{aligned}$$

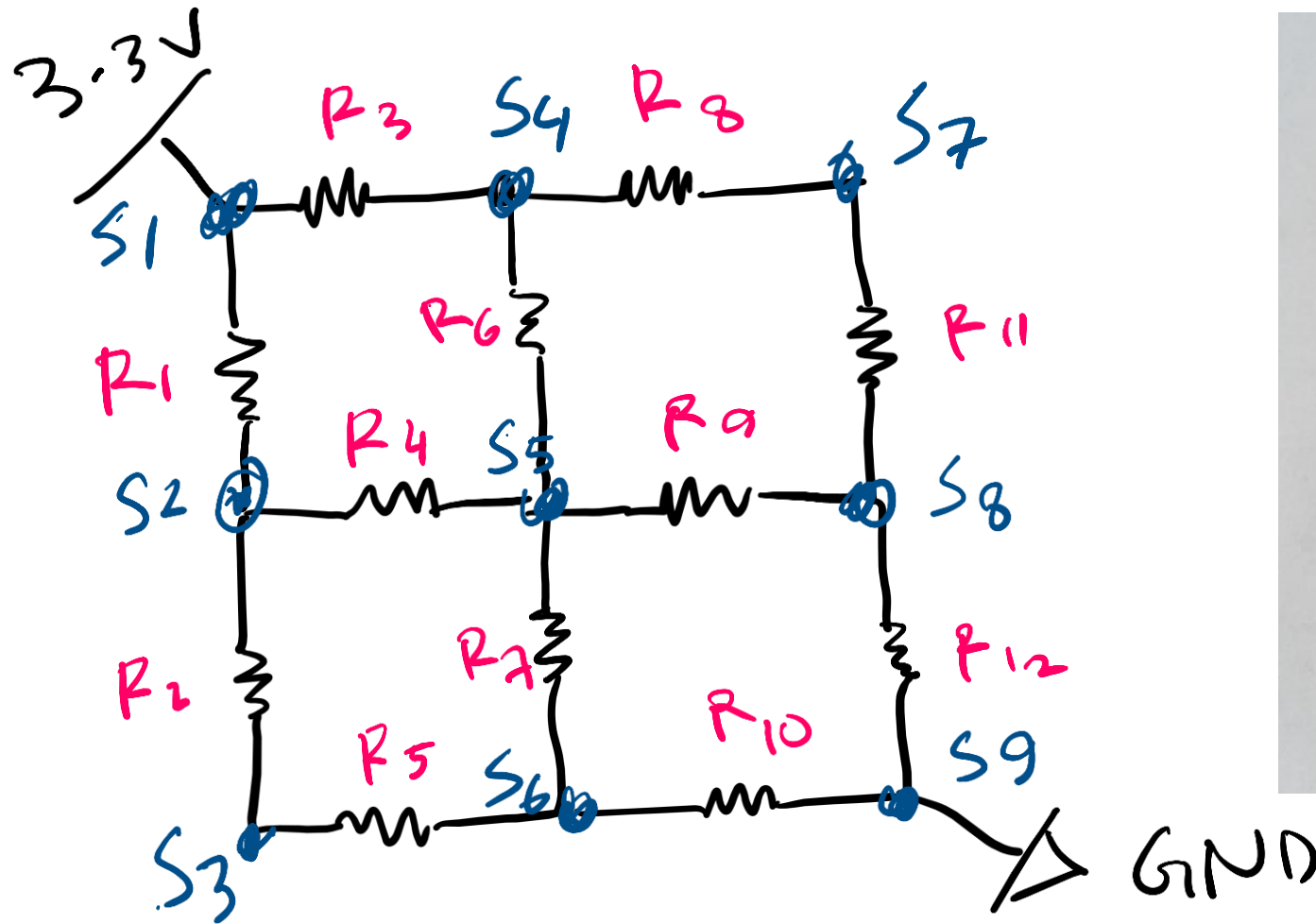
$$\begin{aligned}
 V_{R1} &= S_1 - S_2 = i_1 R_1 = S_1 - S_2 \\
 V_{R2} &= i_2 R_2 = S_2 - S_3 \\
 V_{R3} &= i_3 R_3 = S_1 - S_4 \\
 V_{R4} &= i_4 R_4 = S_2 - S_5 \\
 V_{R5} &= i_5 R_5 = S_3 - S_6 \\
 i_{R6} &= S_4 - S_5 \\
 i_{R7} &= S_5 - S_6 \\
 i_{R8} &= S_4 - S_7 \\
 i_{R9} &= S_5 - S_8 \\
 i_{R10} &= S_6 - S_9 \\
 i_{R11} &= S_7 - S_8 \\
 i_{R12} &= S_8 - S_9
 \end{aligned}$$

gen

gen

AX = y

# Touchpad – Network 2 in the demo board

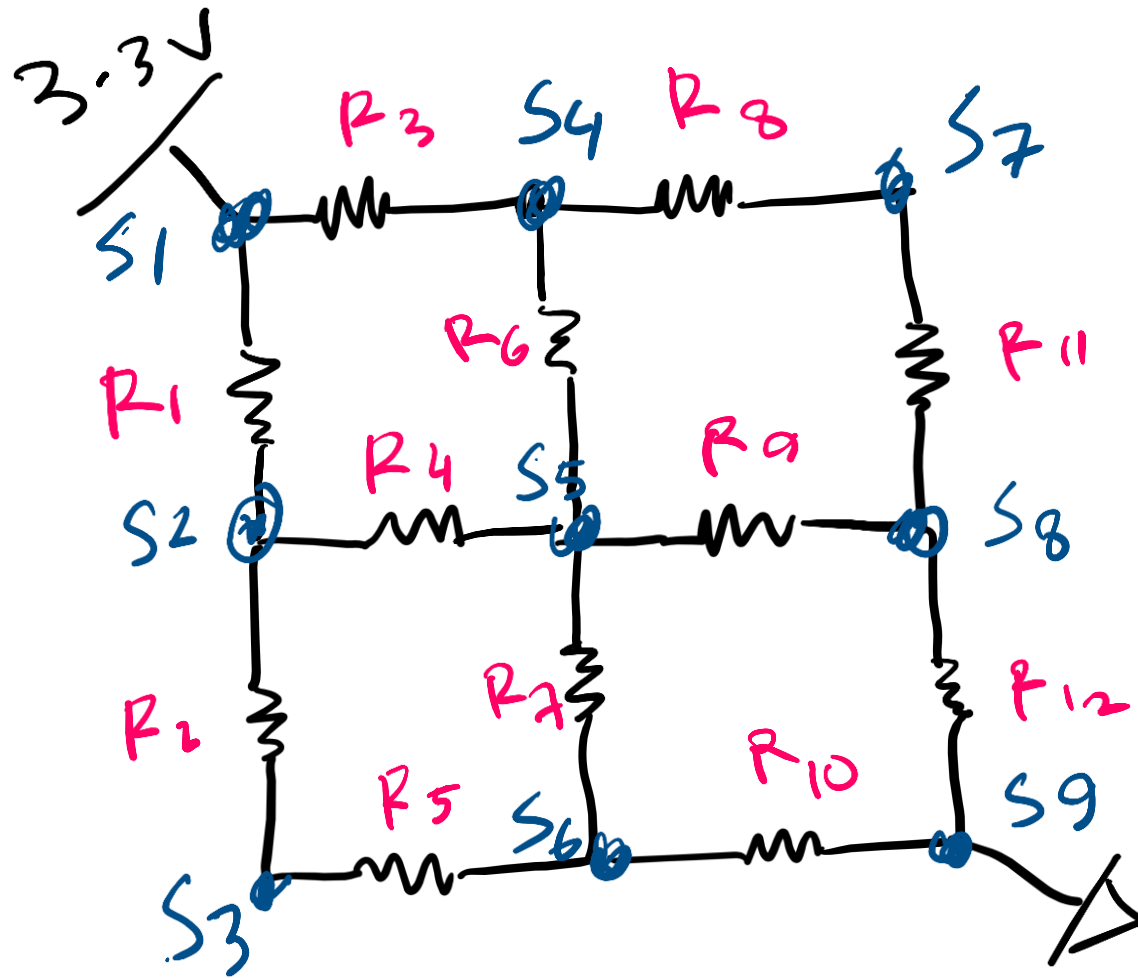


$$\begin{aligned}
 i_t &= i_{R1} + i_{R3} \\
 i_{R1} &= i_{R2} + i_{R4} \\
 i_{R3} &= i_{R6} + i_{R8} \\
 i_{R2} &= i_{R5} \\
 i_{R8} &= i_{R11} \\
 i_{R4} + i_{R6} &= i_{R7} + i_{R9} \\
 i_{R5} + i_{R7} &= i_{R10} \\
 i_{R9} + i_{R11} &= i_{R12} \\
 i_{R10} + i_{R12} &= i_t
 \end{aligned}$$

$$\begin{aligned}
 V_{R1} &= S_1 - S_2 = i_1 R_1 = S_1 - S_2 \\
 V_{R2} &= i_2 R_2 = S_2 - S_3 \\
 V_{R3} &= i_3 R_3 = S_1 - S_4 \\
 V_{R4} &= i_4 R_4 = S_2 - S_5 \\
 V_{R5} &= i_5 R_5 = S_3 - S_6 \\
 i_{R6} &= S_4 - S_5 \\
 i_{R7} &= S_5 - S_6 \\
 i_{R8} &= S_4 - S_7 \\
 i_{R9} &= S_5 - S_8 \\
 i_{R10} &= S_6 - S_9 \\
 i_{R11} &= S_7 - S_8 \\
 i_{R12} &= S_8 - S_9
 \end{aligned}$$

$Ax = y$   
 $g_{2N}$   
 $g_{1N}$

# Touchpad – Network 2 in the demo board

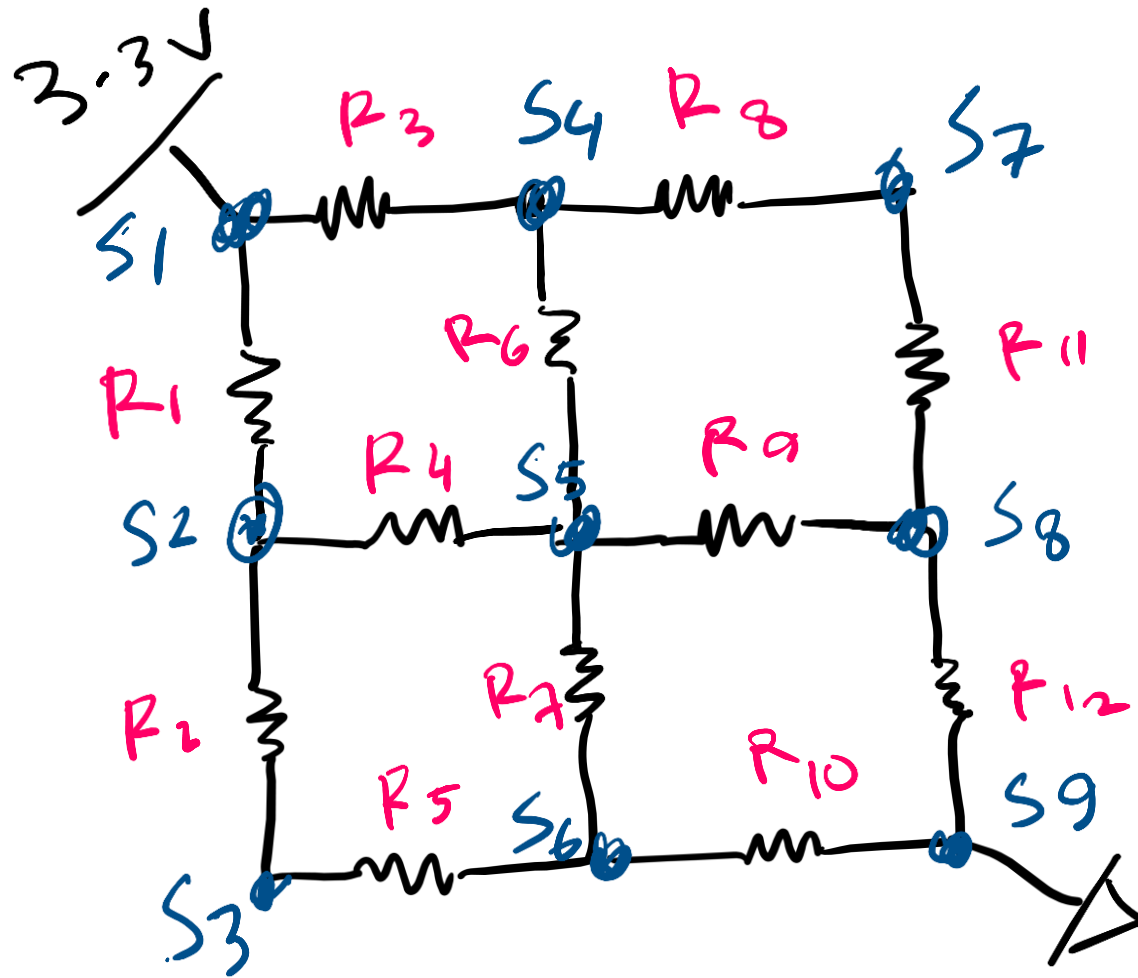


1.  $i_t = i_1 + i_3$
2.  $i_1 = i_2 + i_4$
3.  $i_3 = i_6 + i_8$
4.  $i_2 = i_5$
5.  $i_8 = i_{11}$
6.  $i_4 + i_6 = i_7 + i_9$
7.  $i_5 + i_7 = i_{10}$
8.  $i_9 + i_{11} = i_{12}$
9.  $i_{10} + i_{12} = i_t$
10.  $i_1 \cdot r_1 = s_1 - s_2$
11.  $i_2 \cdot r_2 = s_2 - s_3$
12.  $i_3 \cdot r_3 = s_1 - s_4$
13.  $i_4 \cdot r_4 = s_2 - s_5$
14.  $i_5 \cdot r_5 = s_3 - s_6$
15.  $i_6 \cdot r_6 = s_4 - s_5$
16.  $i_7 \cdot r_7 = s_5 - s_6$
17.  $i_8 \cdot r_8 = s_4 - s_7$
18.  $i_9 \cdot r_9 = s_5 - s_8$
19.  $i_{10} \cdot r_{10} = s_6 - s_9$
20.  $i_{11} \cdot r_{11} = s_7 - s_8$
21.  $i_{12} \cdot r_{12} = s_8 - s_9$

With the conditions:

- $r_1 = r_2 = r_3 = r_4 = r_5 = r_6 = r_7 = r_8 = r_9 = r_{10} = r_{11} = r_{12} = 100$
- $s_1 = 3.3$
- $s_9 = 0$

# Touchpad – Network 2 in the demo board



The solution to the system of equations is as follows:

- $i1 = 0.011$
- $i2 = 0.0055$
- $i3 = 0.011$
- $i4 = 0.0055$
- $i5 = 0.0055$
- $i6 = 0.0055$
- $i7 = 0.0055$
- $i8 = 0.0055$
- $i9 = 0.0055$
- $i10 = 0.011$
- $i11 = 0.0055$
- $i12 = 0.011$
- $it = 0.022$

The intermediate variables are:

- $s2 = 2.2$
- $s3 = 1.65$
- $s4 = 2.2$
- $s5 = 1.65$
- $s6 = 1.1$
- $s7 = 1.65$
- $s8 = 1.1$